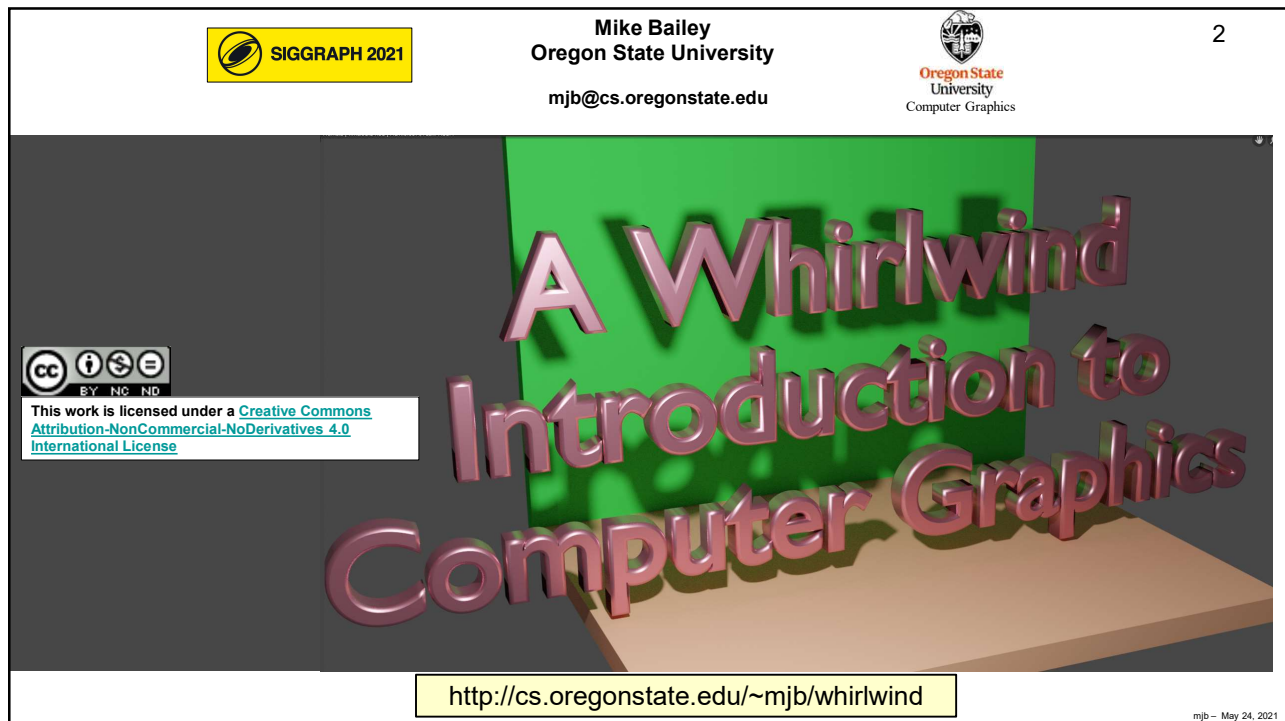




1



2

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SIGGRAPH '21 Educator's Forum, August 09-13, 2021, Virtual Event, USA

ACM 978-1-4503-8363-9/21/08.

10.1145/3450549.3464408

Course Goals

- Provide a background for the amazing things you will hear about in the other SIGGRAPH 2021 venues
- Create an understanding of common computer graphics vocabulary
- Help you understand the significance of the images and animations that you will see
- Provide references for further study

<http://cs.oregonstate.edu/~mjb/whirlwind>

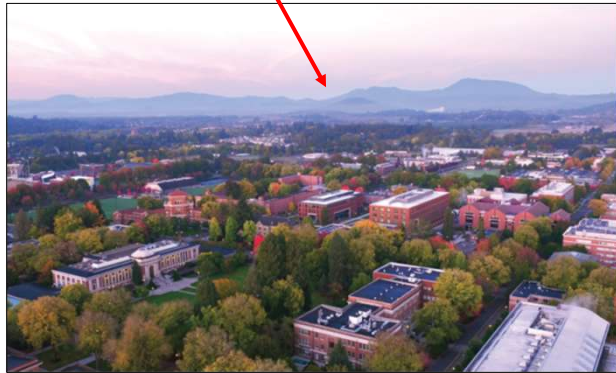


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Mike Bailey

- Professor of Computer Science, Oregon State University
- Has been in computer graphics for over 30 years
- Has had over 9,000 students in his university classes
- mjb@cs.oregonstate.edu

Welcome! I'm happy to be here. I hope you are too!



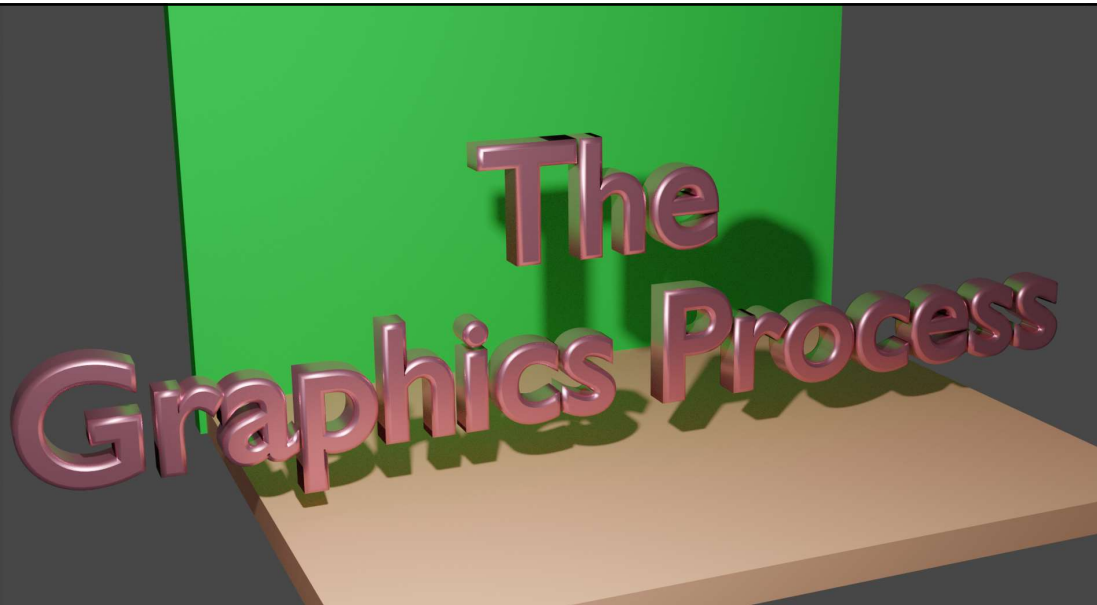
<http://cs.oregonstate.edu/~mjb/whirlwind>



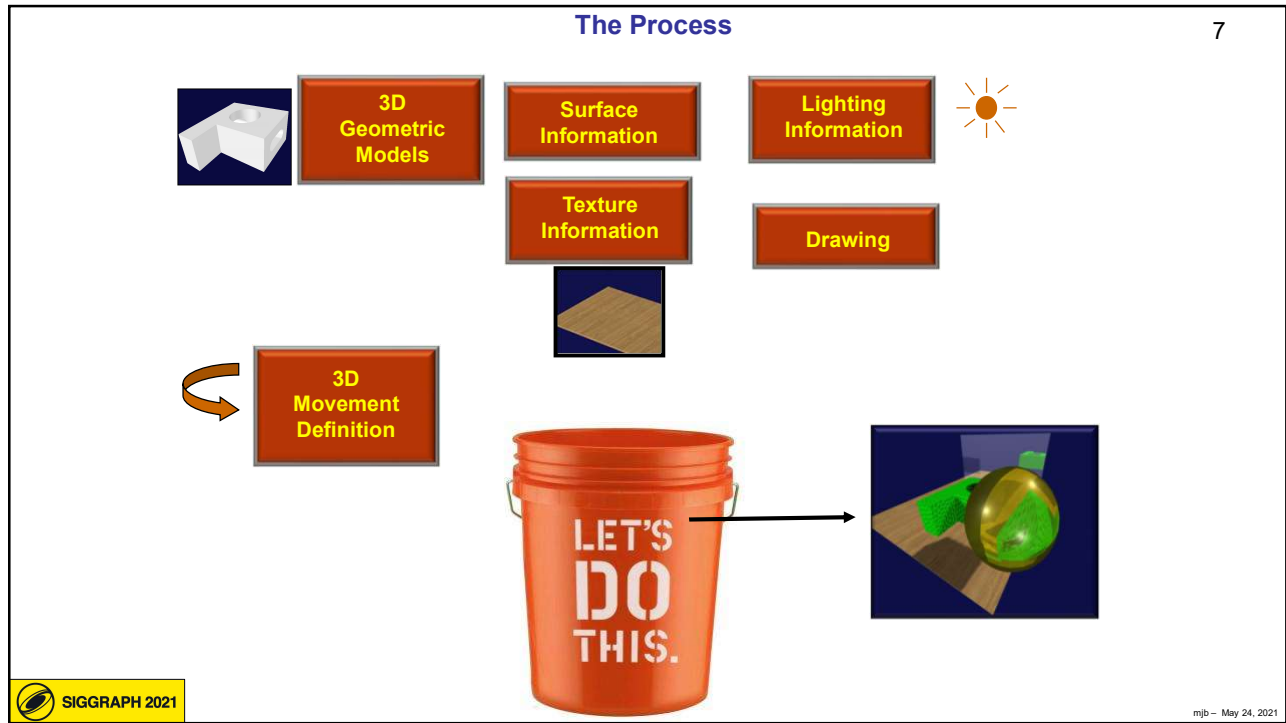
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- How the computer graphics pieces fit together
- Modeling
- Rendering
- Animation
- Finding More Information

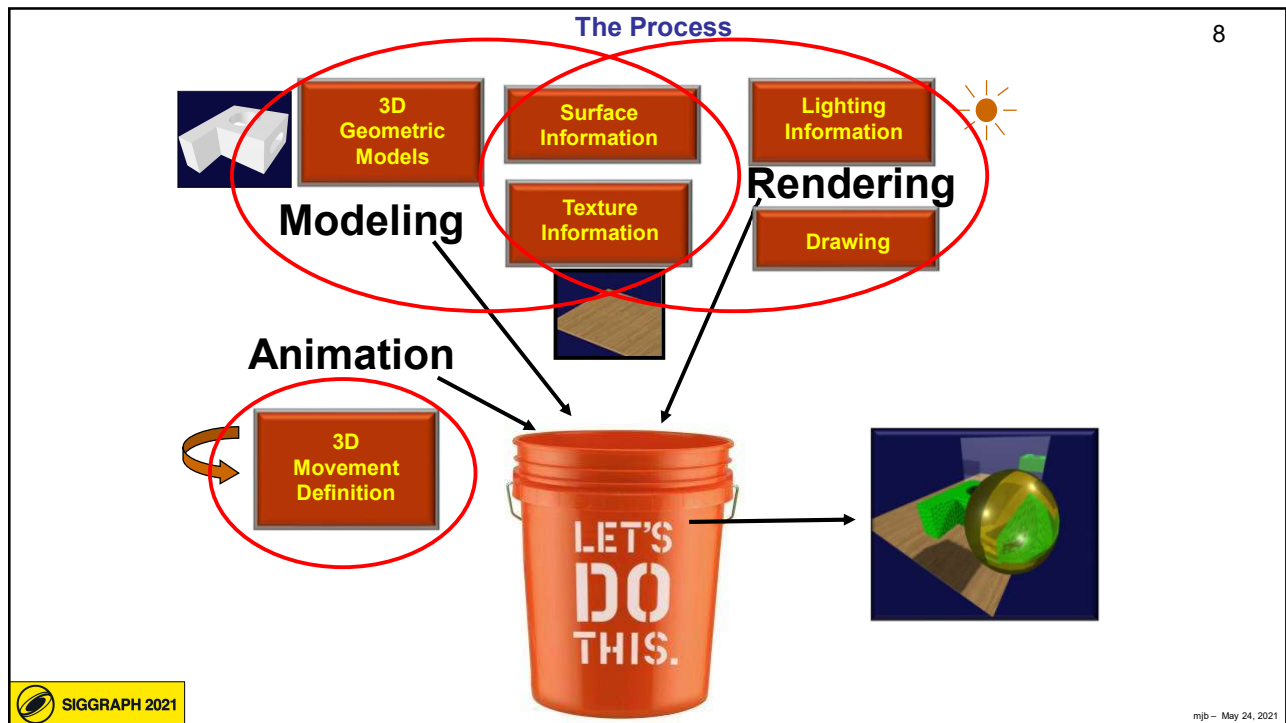
<http://cs.oregonstate.edu/~mjb/whirlwind>



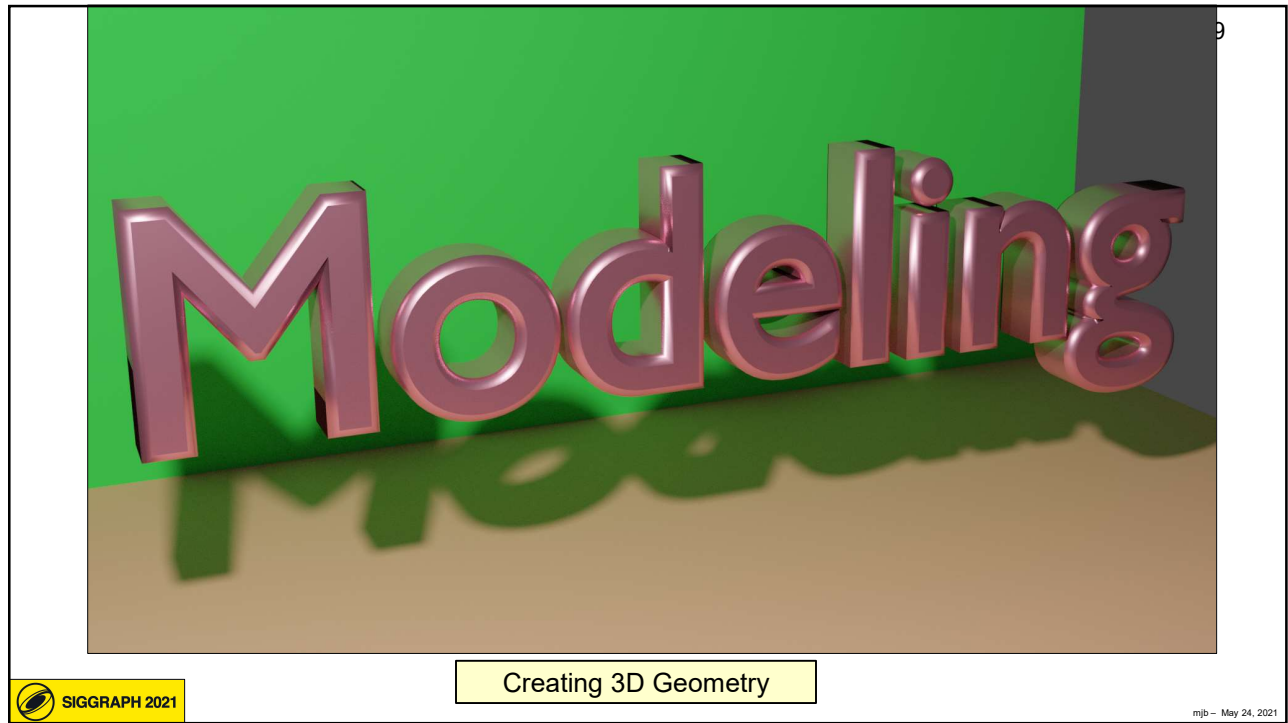
What are all the pieces that go into making the graphics you will be see?
What does it take to make them?



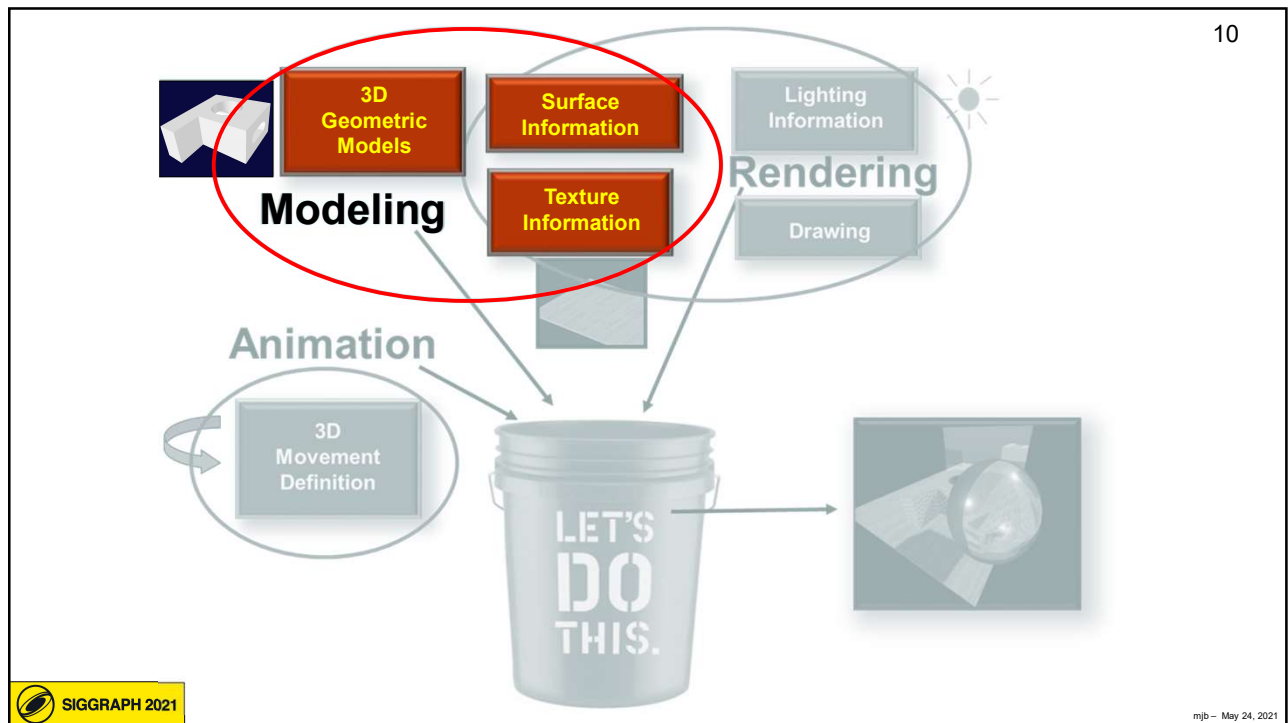
7



8



9



10

What do we mean by “Modeling”?

11

In computer graphics applications, how we model geometry depends on what we would like to use the geometry for:

- Looking at its appearance
- Interacting with its shape?
- How does it interact with its environment?
- What is its surface area and volume?
- Will it be able to be 3D-printed?
- Etc.

Want to experiment with some free modeling programs?

Want some notes on how to get started?

<http://cs.oregonstate.edu/~mjb/blender>

<http://cs.oregonstate.edu/~mjb/sketchup>

<http://cs.oregonstate.edu/~mjb/tinkercad>



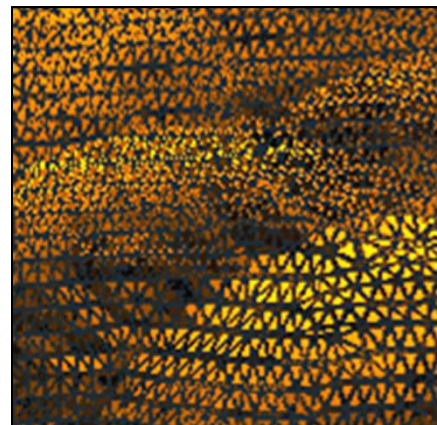
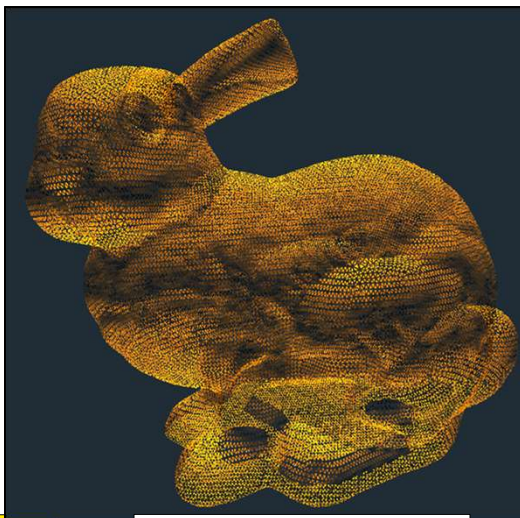
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11

Explicitly Listing Geometry and Topology

12

Models defined this way can consist of thousands of vertices and faces – we need some way to describe them effectively



This is often called a **Mesh**.



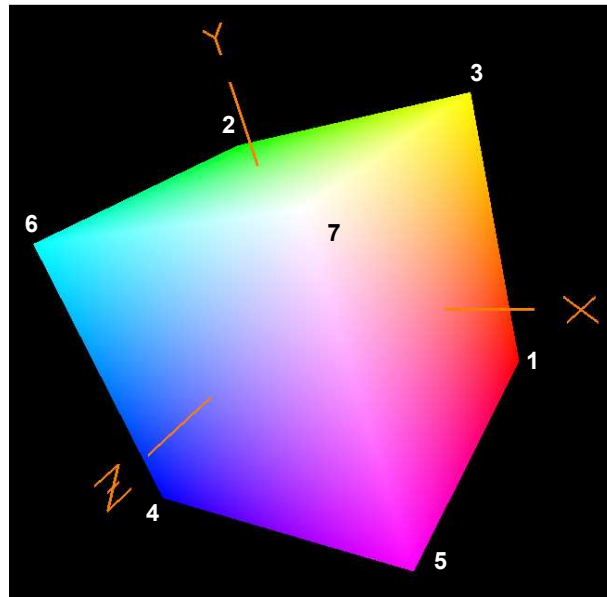
<http://graphics.stanford.edu/data/3Dscanrep>

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Cube Mesh Example

13

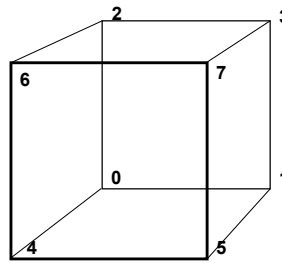
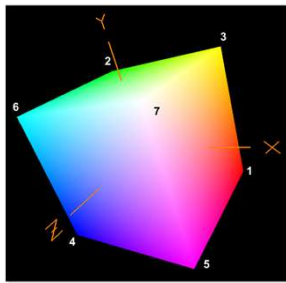


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13

Explicitly Listing Geometry and Topology -- Quadrilaterals

14



```
static GLfloat CubeVertices[][3] =
{
    { -1., -1., -1. },
    { 1., -1., -1. },
    { -1., 1., -1. },
    { 1., 1., -1. },
    { -1., -1., 1. },
    { 1., -1., 1. },
    { -1., 1., 1. },
    { 1., 1., 1. }
};
```

```
static GLfloat CubeColors[][3] =
{
    { 0., 0., 0. },
    { 1., 0., 0. },
    { 0., 1., 0. },
    { 1., 1., 0. },
    { 0., 0., 1. },
    { 1., 0., 1. },
    { 0., 1., 1. },
    { 1., 1., 1. }
};
```

```
static GLuint CubeIndices[][4] =
{
    { 0, 2, 3, 1 },
    { 4, 5, 7, 6 },
    { 1, 3, 7, 5 },
    { 0, 4, 6, 2 },
    { 2, 6, 7, 3 },
    { 0, 1, 5, 4 }
};
```

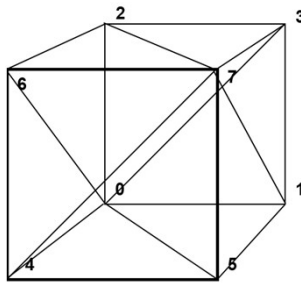
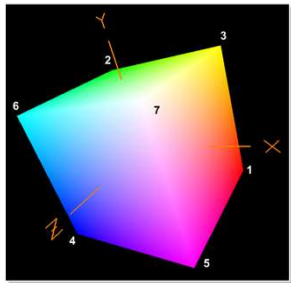


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More likely we would use Triangles

15



```
GLuint TriangleCubeIndices[ ][3] =
{
    { 0, 2, 3 },
    { 0, 3, 1 },
    { 4, 5, 7 },
    { 4, 7, 6 },
    { 1, 3, 7 },
    { 1, 7, 5 },
    { 0, 4, 6 },
    { 0, 6, 2 },
    { 2, 6, 7 },
    { 2, 7, 3 },
    { 0, 1, 5 },
    { 0, 5, 4 }
};
```

```
GLuint CubeIndices[ ][4] =
{
    { 0, 2, 3, 1 },
    { 4, 5, 7, 6 },
    { 1, 3, 7, 5 },
    { 0, 4, 6, 2 },
    { 2, 6, 7, 3 },
    { 0, 1, 5, 4 }
};
```

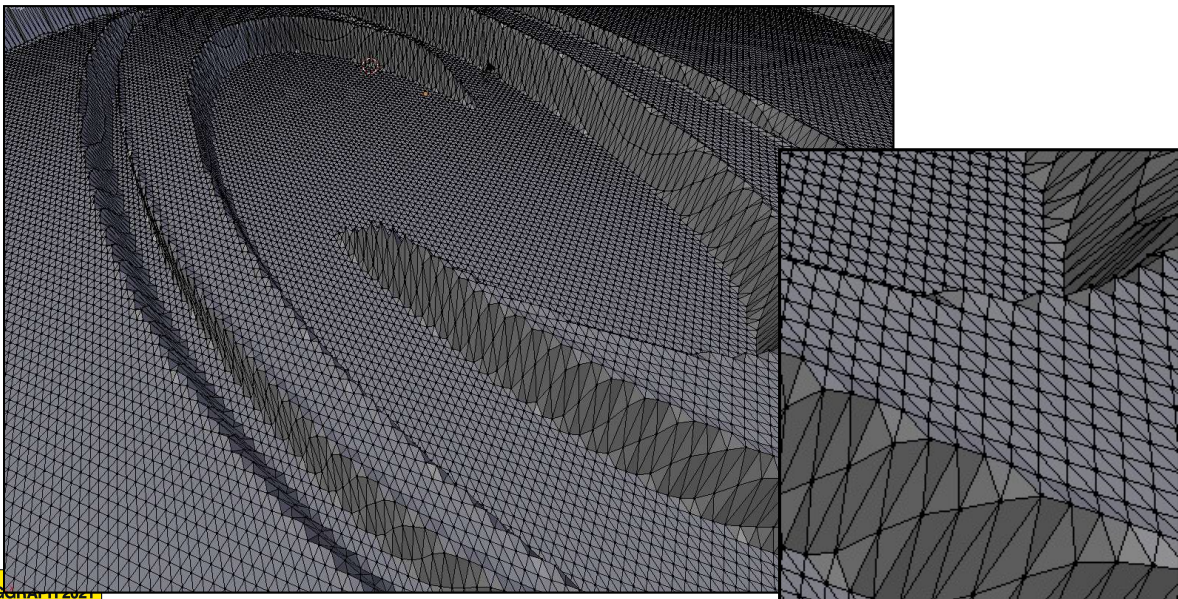


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15

Triangular Meshes are Very Important These Days Because 3D Printing Requires a Triangular Mesh Data Format

16

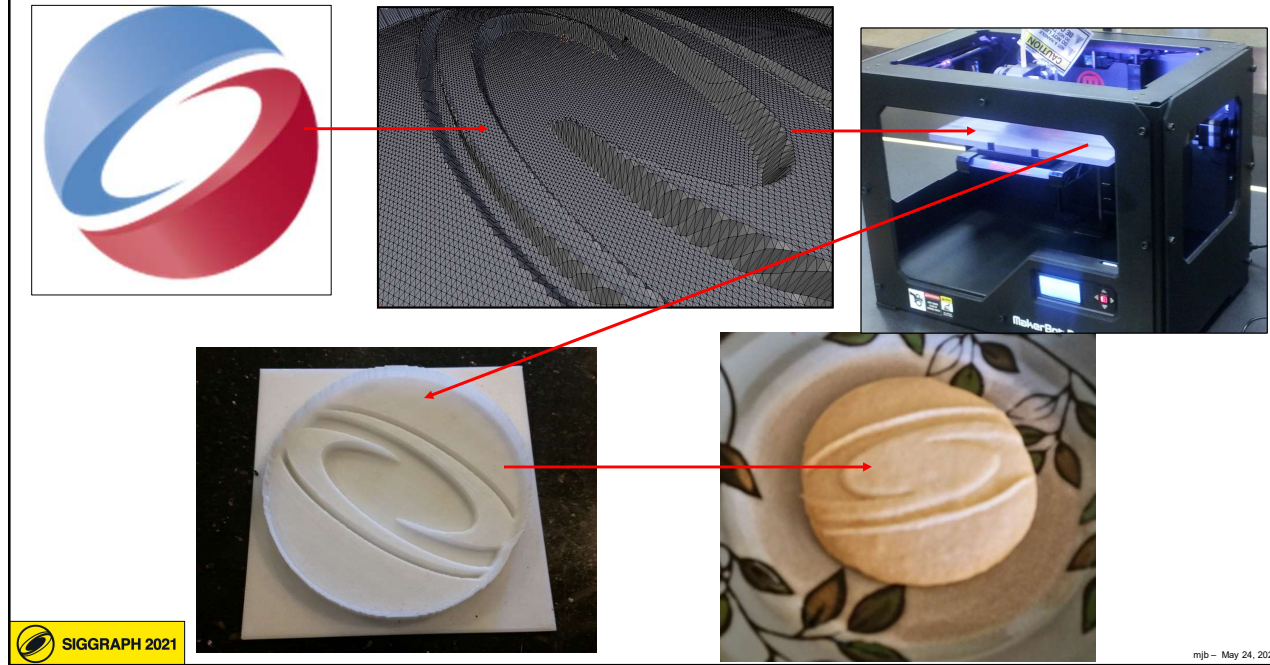


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16

3D geometric modeling at its very best -- mmmm... :-)

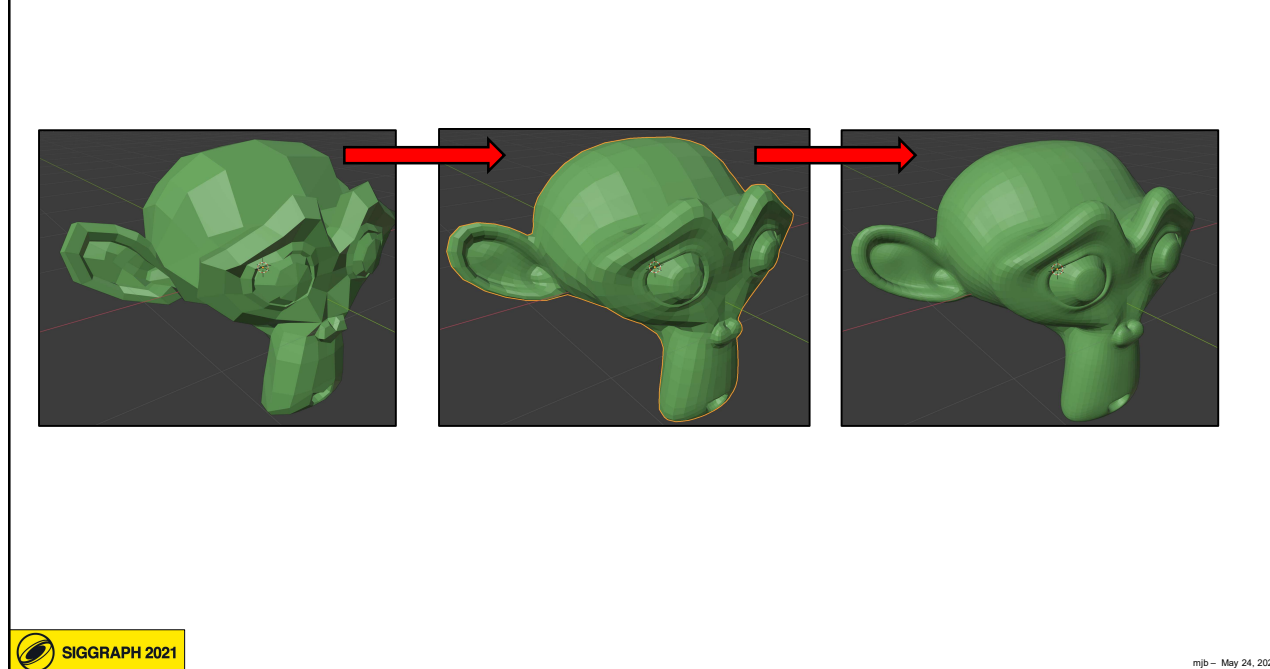
17



17

Meshes Can Be Smoothed

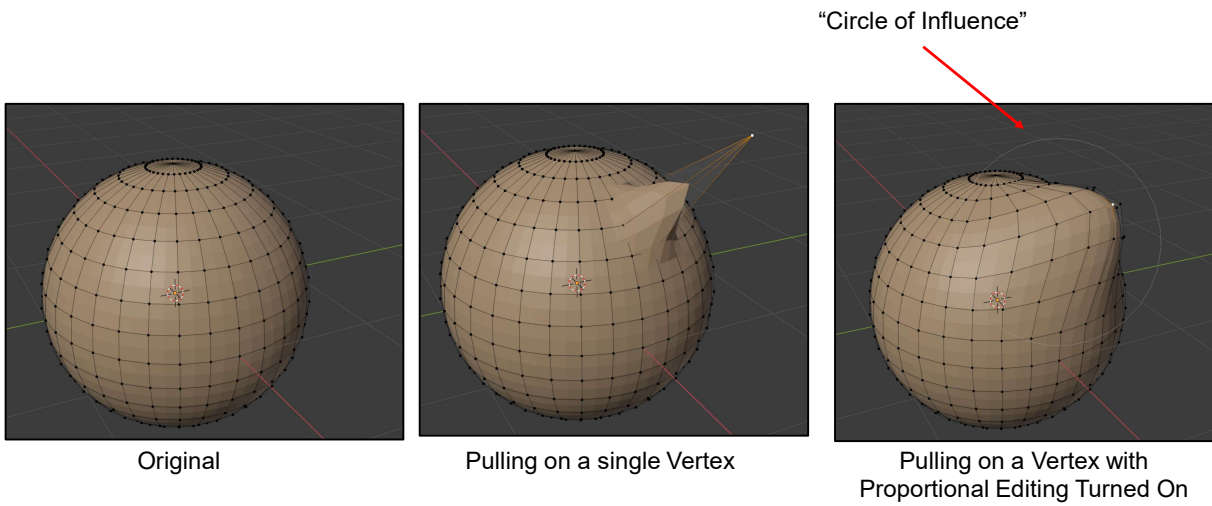
18



18

Meshes Can Be Edited

19

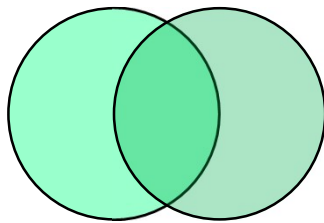


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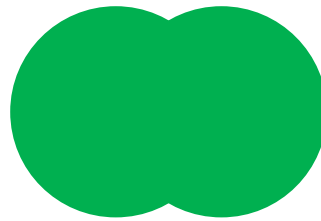
19

Another way to Model: Remember Venn Diagrams (2D Boolean Operators)?

20



Two Overlapping Shapes



Union



Intersection



Difference

I thought I left this behind in High School!

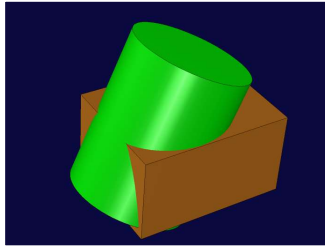


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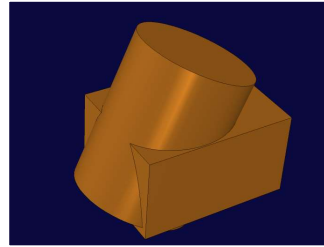
20

Solid Modeling Using 3D Boolean Operators

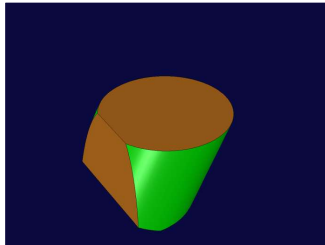
21



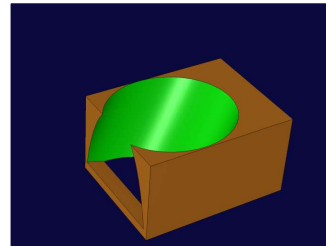
Two Overlapping Solids



Union



Intersection



Difference



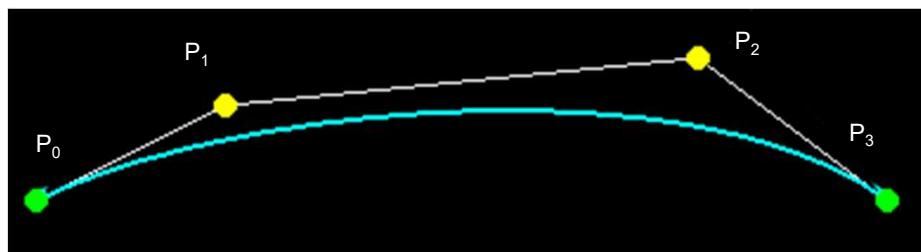
This is often called **Constructive Solid Geometry**, or **CSG**

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Another way to Model: Curve Sculpting – Bézier Curve Sculpting

22



$$P(t) = (1-t)^3 P_0 + 3t(1-t)^2 P_1 + 3t^2(1-t) P_2 + t^3 P_3$$
$$0 \leq t \leq 1.$$

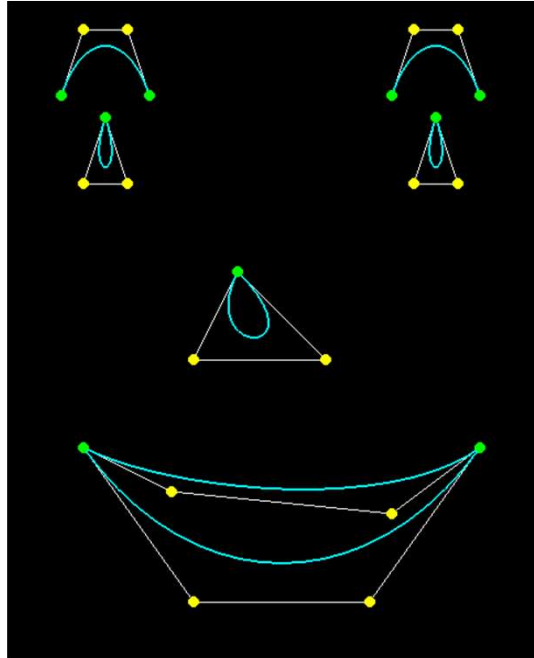


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22

Curve Sculpting –Bézier Curve Sculpting Example

23



curves.mp4

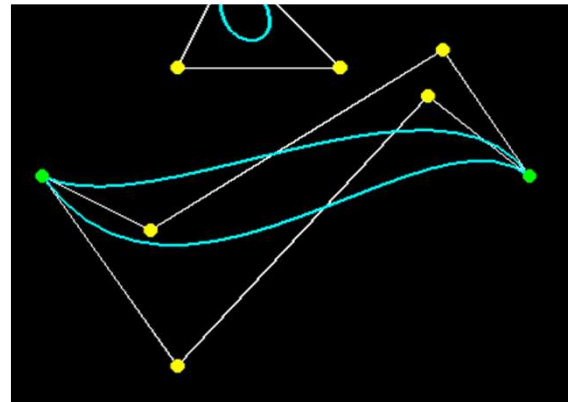
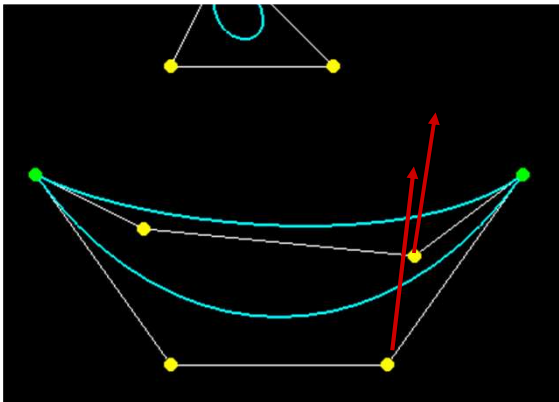


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Curve Sculpting –Bézier Curve Sculpting Example

24



A *Small* Amount of Input Change Results in a *Large* Amount of Output Change



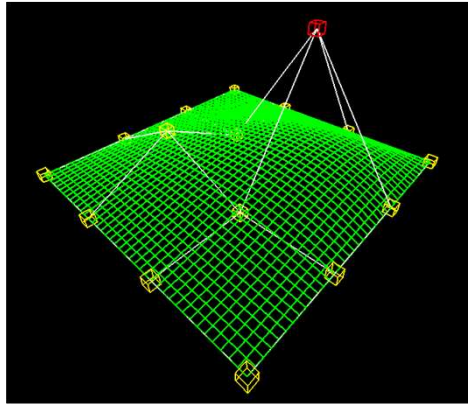
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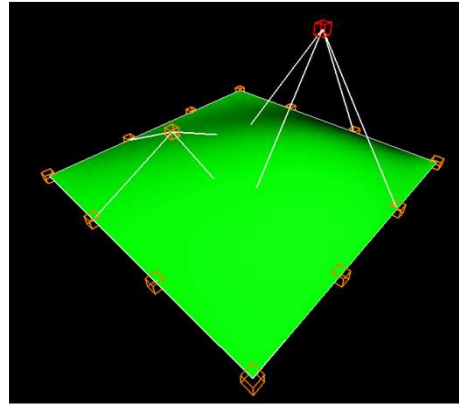
Another way to Model: Surface Sculpting

25

In general, these are referred to as **Patches**. These, in particular, are Beziér patches.
Non-uniform Rational B-spline Surfaces, or NURBS, are another popular type.



Wireframe



Surface

Like the curve sculpting, a *Small* Amount of Input
Change Results in a *Large* Amount of Output Change

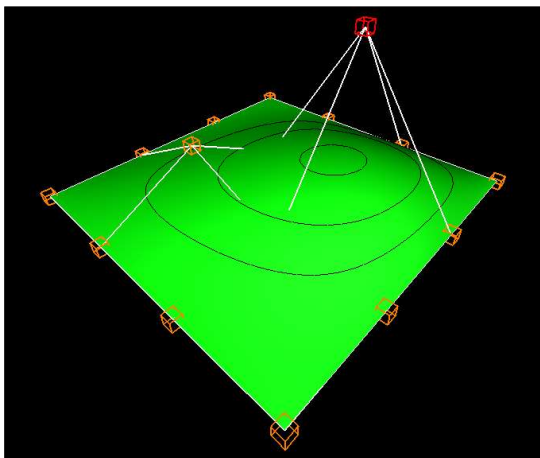


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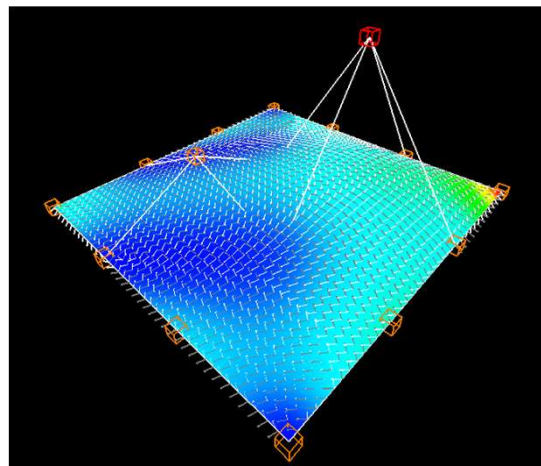
25

Surface Equations can also be used for Analysis

26



Showing Contour Lines



Showing Curvature

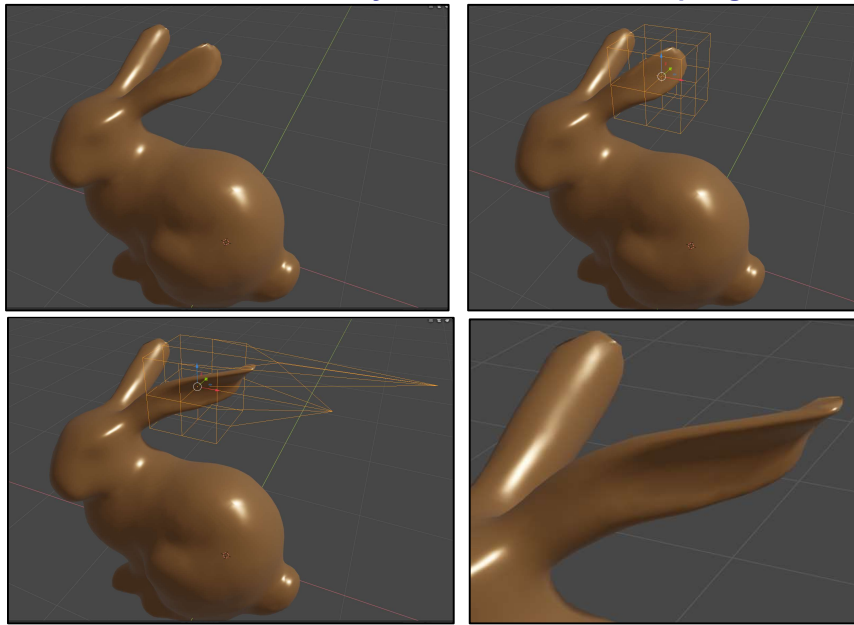


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Another Way to Model: Volume Sculpting

27



lattice.mp4

This is often called a “**Lattice**” or a “**Cage**”.

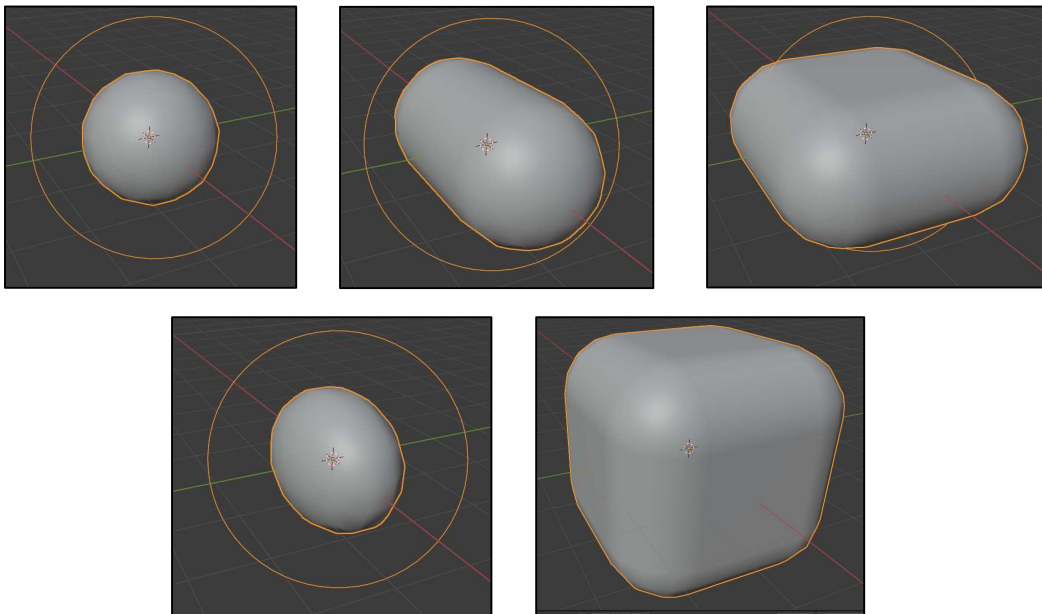


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27

Metaball Objects

28



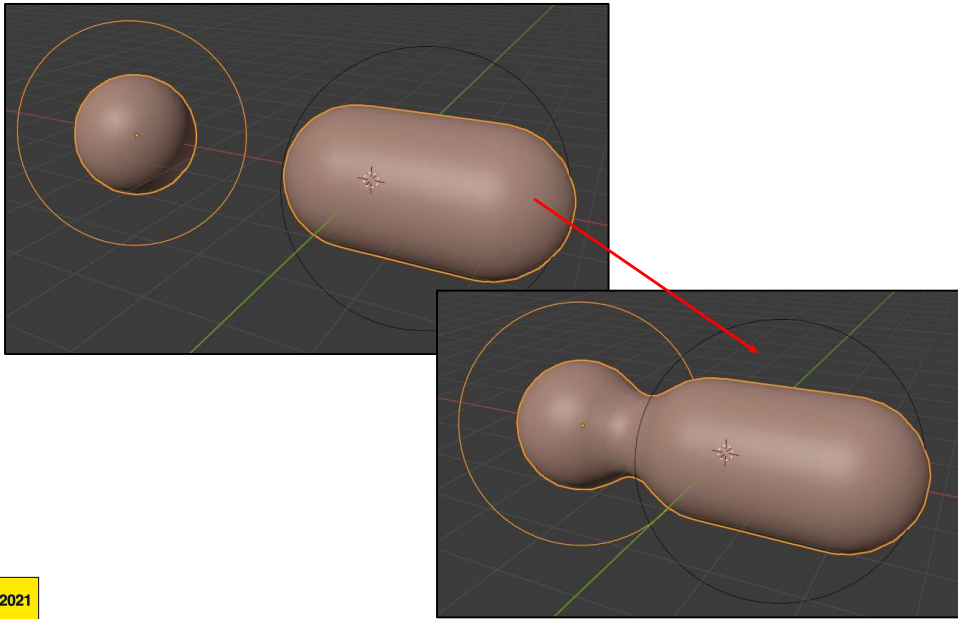
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Metaball Objects

29

The cool thing is that, if you move them close enough together, they will “glom” into a single object

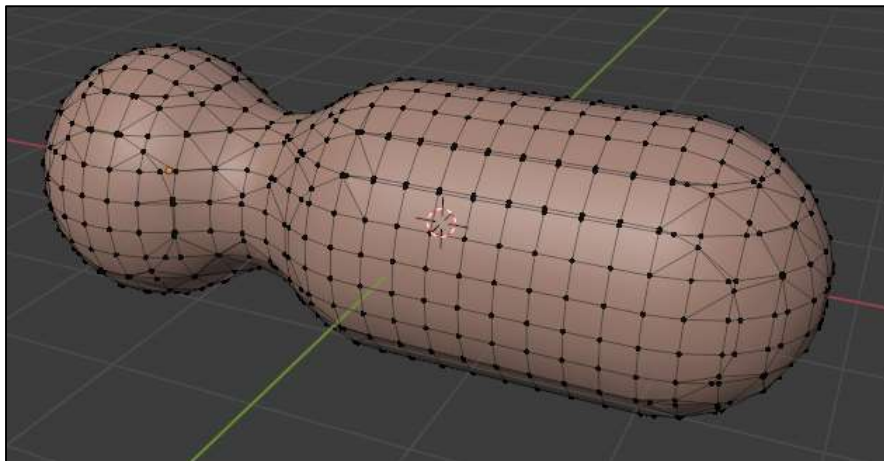


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Metaball Objects Can Be Turned into Meshes for Later Editing

30

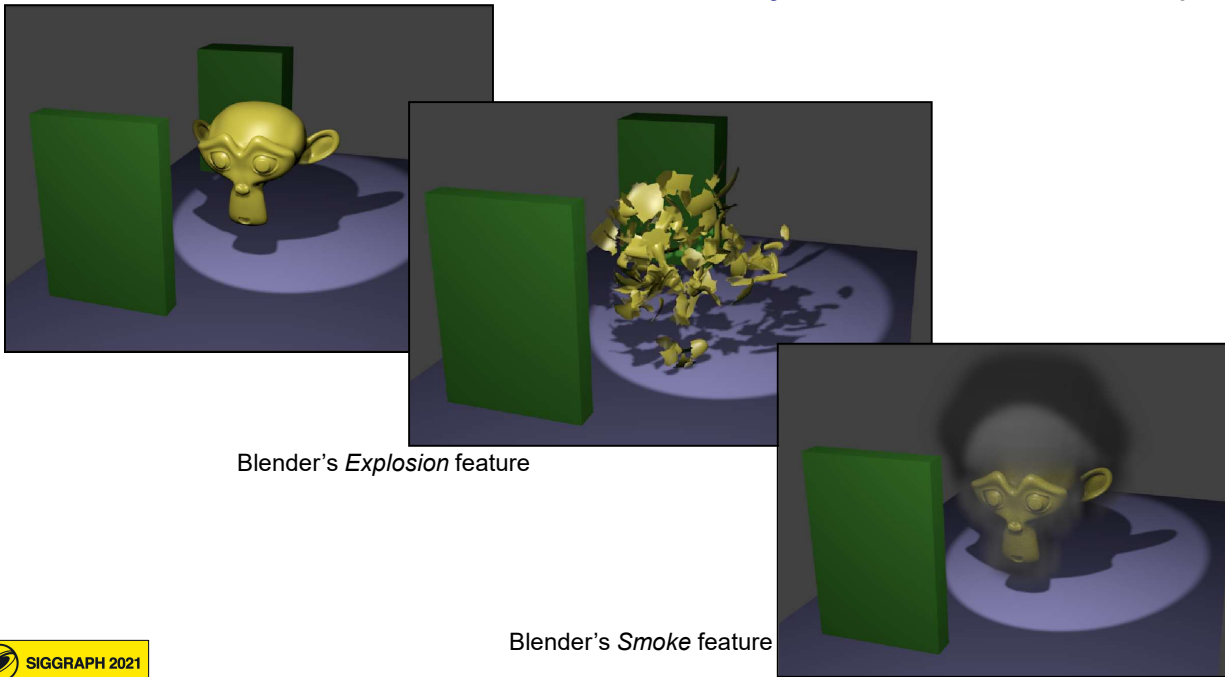


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Geometric Models can also be used for Physical Simulation

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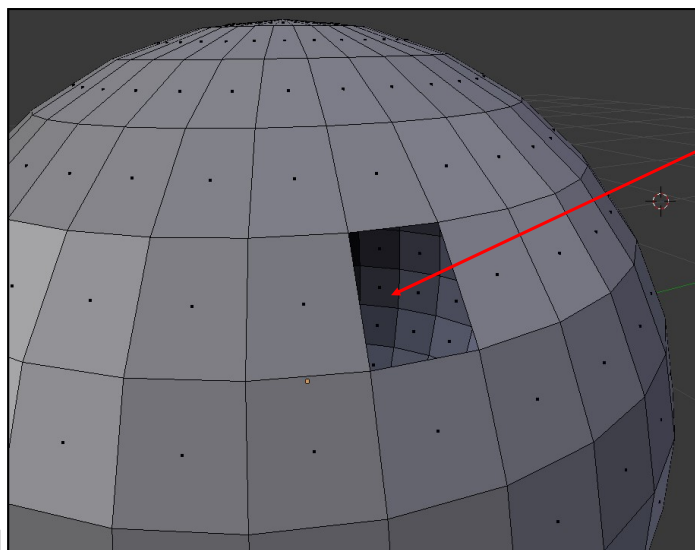


31

Object Modeling Rules for 3D Printing

32

The object must be a legal solid. It must have a definite inside and a definite outside. It can't have any missing face pieces.



Missing face



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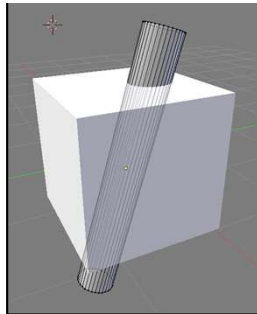
32

Object Modeling Rules for 3D Printing

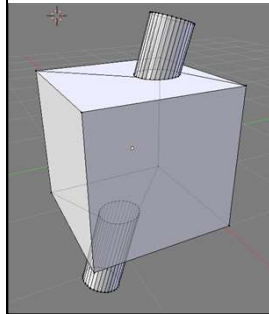
33

Objects cannot pass through other objects. If you want two shapes together, do a CSG union on them so that they become one complete object.

Overlapping in 3D -- **bad**



Boolean union -- **good**



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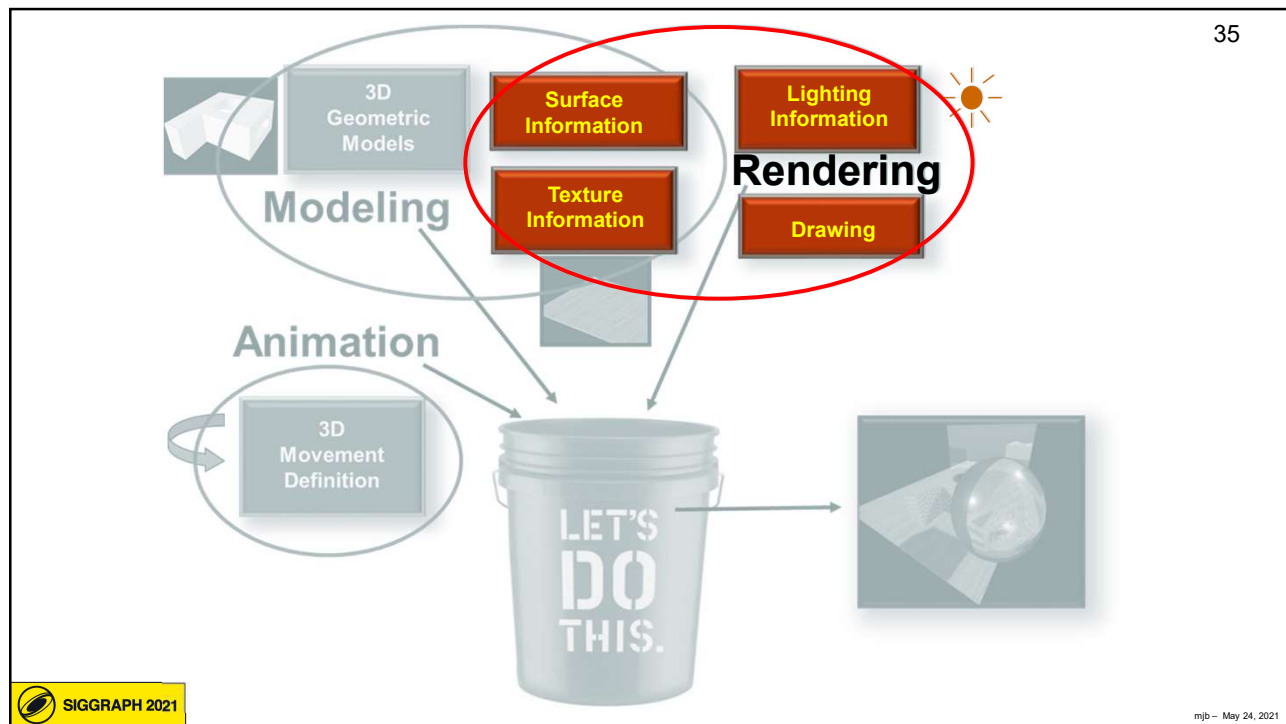
34



Creating an image

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Rendering

Rendering is the process of creating an image of geometric modes. Again, there are questions you need to ask first:

- Why am I doing this?
- How realistic do I want this image to be?
- How much compute time do I want this to take?
- Do I need to take lighting into account?
- Does the illumination need to be global or will local do?
- Do I need to create shadows?
- Do I need to create reflections and refractions?

Want to experiment with a free rendering program?
Want some notes on how to get started?
<http://cs.oregonstate.edu/~mjb/blender>

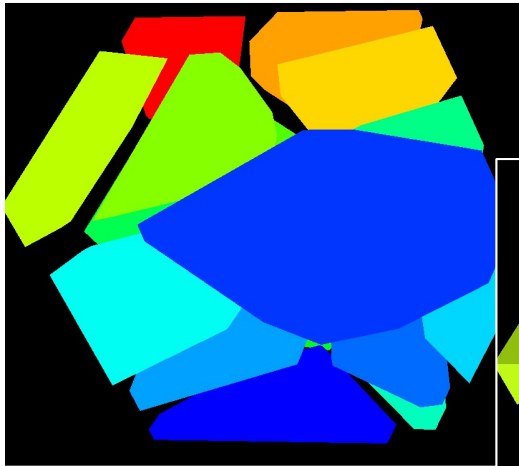
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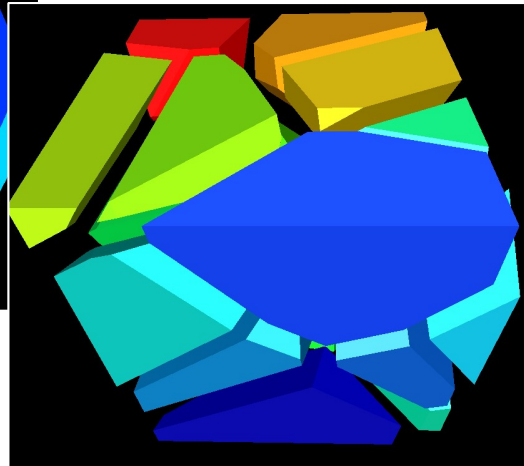
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Why Do We Care About Lighting?

No lighting



Lighting



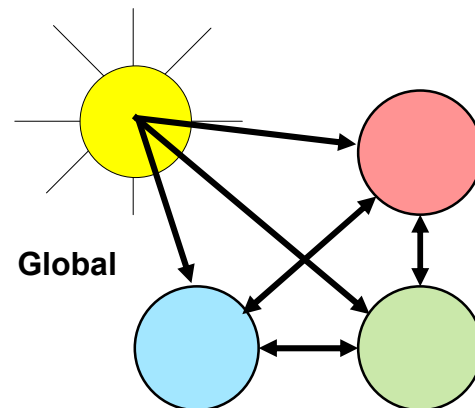
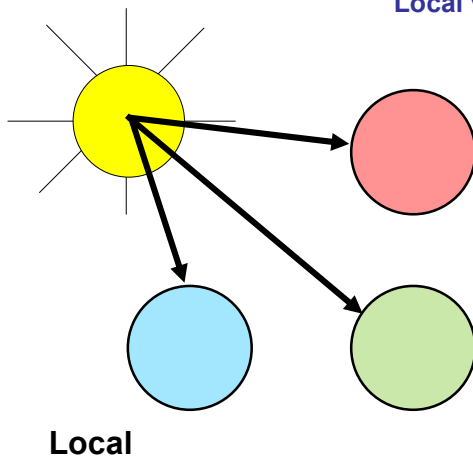
Lighting makes it possible to tell the difference between surfaces or parts of surfaces



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Local vs. Global Illumination

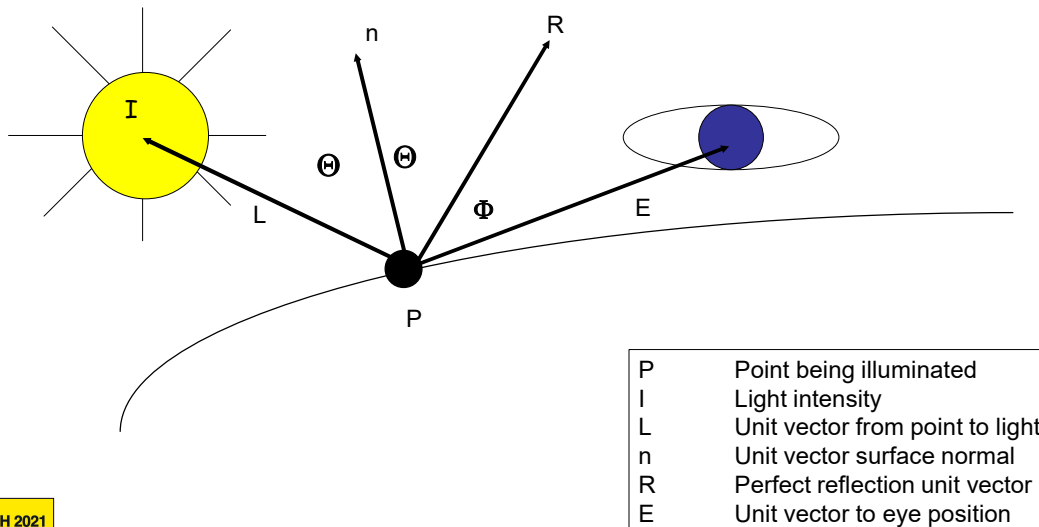


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A Common type of Local Illumination: Ambient-Diffuse-Specular (ADS)

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A Common type of Local Illumination: Ambient-Diffuse-Specular (ADS)

40

1. Ambient = a constant Accounts for light bouncing "everywhere"
2. Diffuse = $I \cdot \cos\Theta$ Accounts for the angle between the incoming light and the surface normal
3. Specular = $I \cdot \cos^S\phi$ Accounts for the angle between the "perfect reflector" and the eye; also the exponent, S, accounts for surface shininess

Note that $\cos\Theta$ is just the dot product between unit vectors L and n

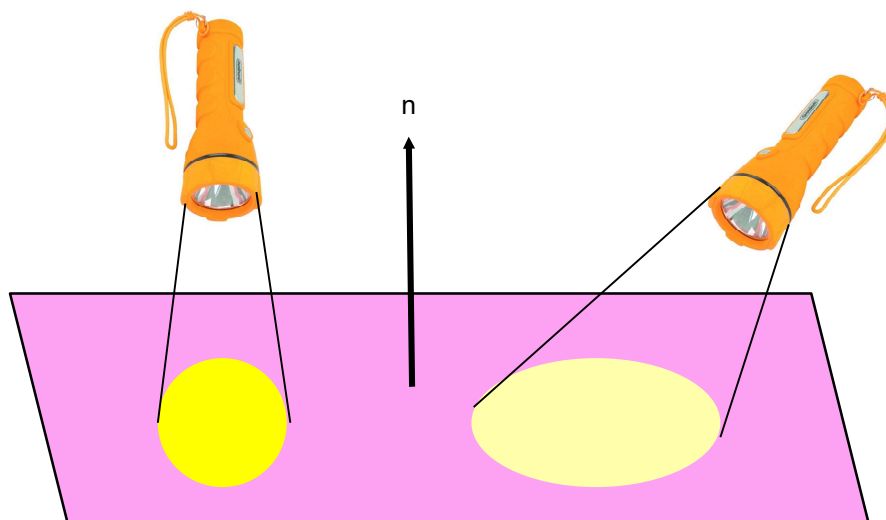
Note that $\cos\phi$ is just the dot product between unit vectors R and E

40

Diffuse Lighting works because of spreading out the same amount of light energy across more surface area

41

$$\text{Diffuse} = I^* \cos \Theta$$



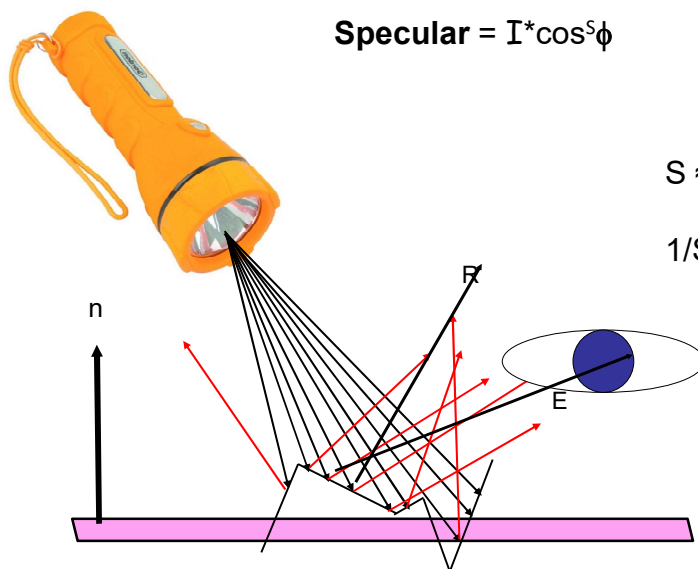
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The Specular Lighting equation is a heuristic that approximates reflection from a rough surface

42

$$\text{Specular} = I^* \cos^S \phi$$



$S \approx$ "shininess"


$1/S \approx$ "roughness"



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42

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Ambient

+




Diffuse

+




Specular


=



Put them all together!



lighting.mp4



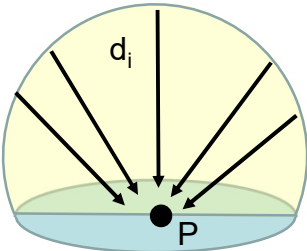
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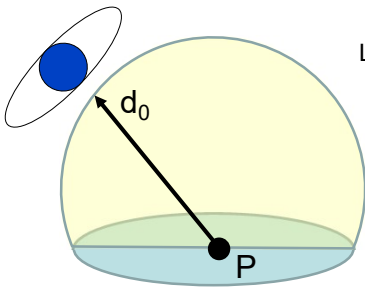
Global Illumination: The Rendering Equation



Ω


Light arriving at Point P from everywhere

$$B(P, d_0, \lambda) = E(P, d_0, \lambda) + \int_{\Omega} B(P, d_i, \lambda) f(\lambda, d_i, d_0) (d_i \cdot \hat{n}) d\Omega$$



d_0

Light departing from Point P in the direction that we are viewing the scene from



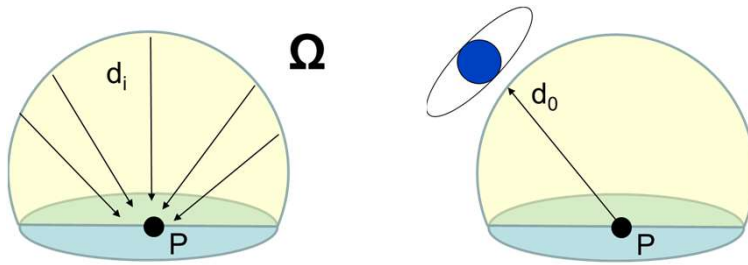
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The Rendering Equation

45



$$B(P, d_0, \lambda) = E(P, d_0, \lambda) + \int_{\Omega} B(P, d_i, \lambda) f(\lambda, d_i, d_0) (d_i \cdot \hat{n}) d\Omega$$

In plain language, this is a light balance equation:

“The light shining from the point P towards your eye is the reflection of the incoming light directed to the point P from all of the other points in the scene.”

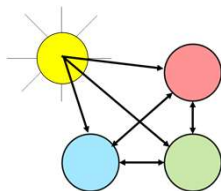


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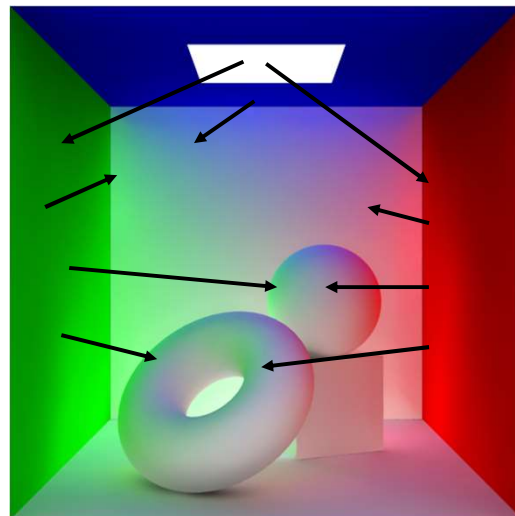
The Lighting Equation at Work

46



- The left wall is green.
- The right wall is red.
- The back wall is white.
- The ceiling is blue with a light source in the middle of it.
- The objects sitting on the floor are white.

If the appearance of an object is also affected by the appearances of other objects, then you have **Global Illumination**.



<http://www.swardson.com/unm/tutorials/mentalRay3/>



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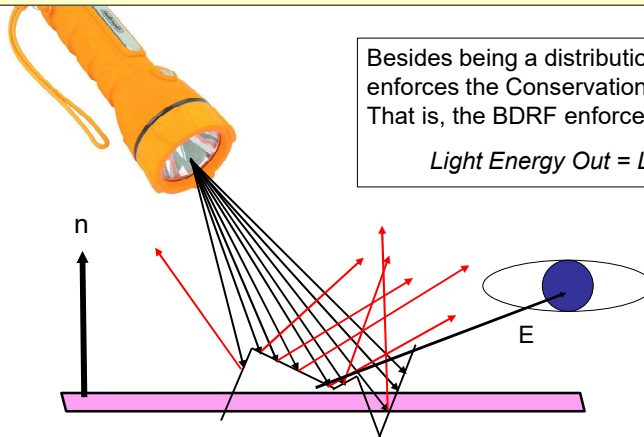
When light hits a surface, it bounces in particular ways depending on the angle and the material

This distribution of bounced light rays is called the **Bidirectional Reflectance Distribution Function**, or **BRDF**.

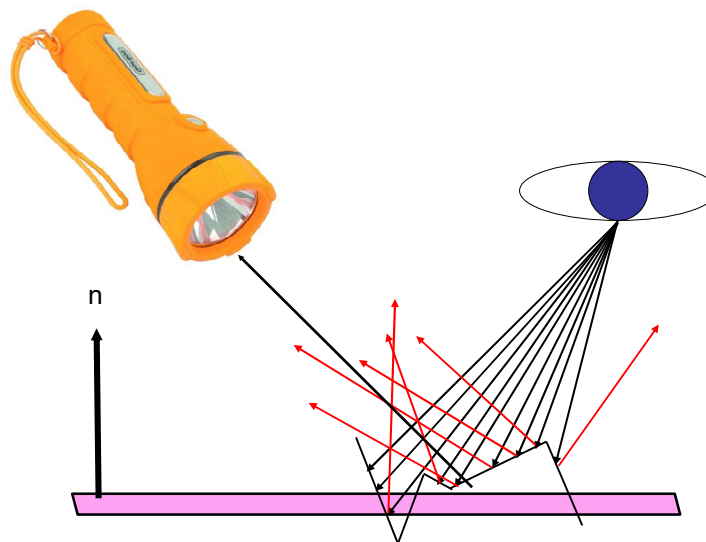
For a given material, the BRDF behavior of a light ray is a function of 4 variables: the 2 spherical coordinates of the incoming ray and the 2 spherical coordinates of the outgoing ray.

Besides being a distribution, the BRDF enforces the Conservation of Energy law. That is, the BRDF enforces

$$\text{Light Energy Out} = \text{Light Energy In}$$



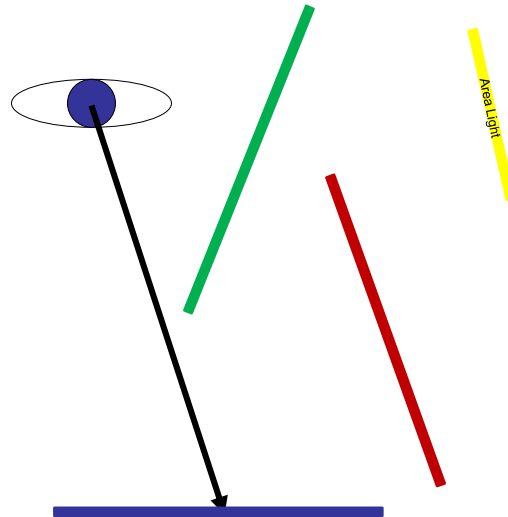
Usually it is easier to trace from the eye



Physically-Based Rendering

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Let light can bounce around the scene, depending on how the different materials behave.

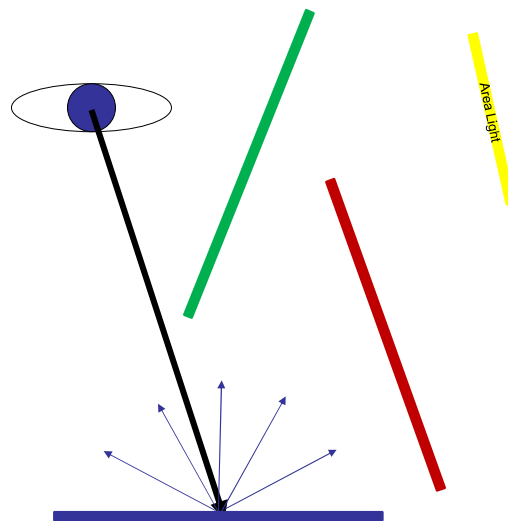


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Physically-Based Rendering

50

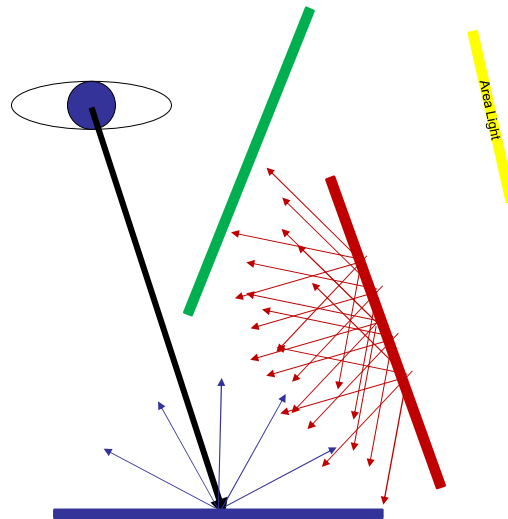
Let light can bounce around the scene, depending on how the different materials behave.



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Physically-Based Rendering

51

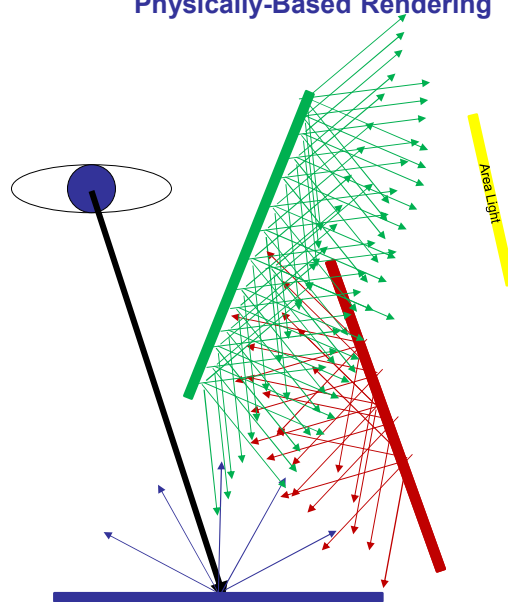


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Physically-Based Rendering

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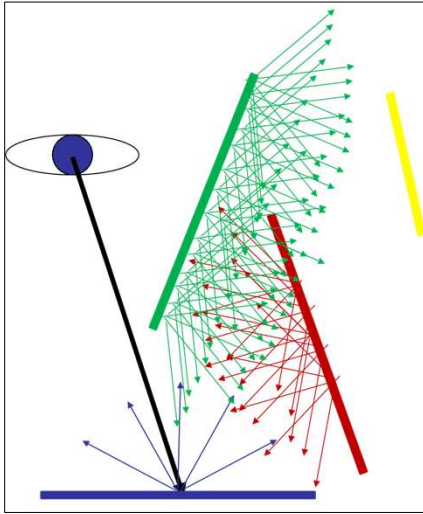


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Physically-Based Rendering

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Clearly this is capable of spawning an infinite number of rays. How do we handle this?

For a small-ish number of bounces, we can evenly distribute a collection of rays.

For lots of bounces, it's **Monte Carlo** simulation to the rescue!

$$LightGathered = \frac{\sum_{i=0}^{N-1} ResultOfRaysCastInRandomDirection}{N}$$

Recurse by applying this equation for all ray hits (yikes!)

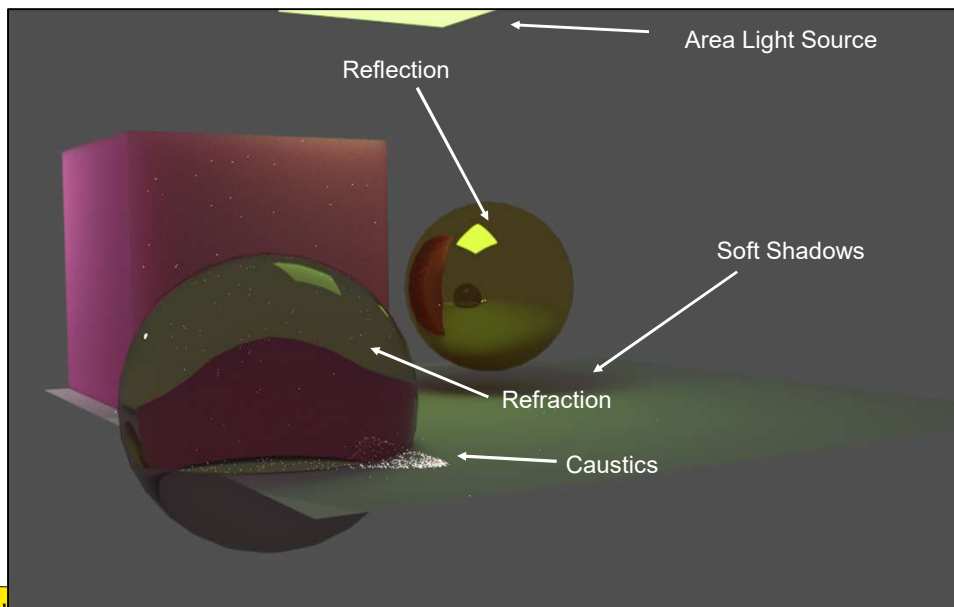


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Physically-Based Rendering using the Blender Cycles Renderer

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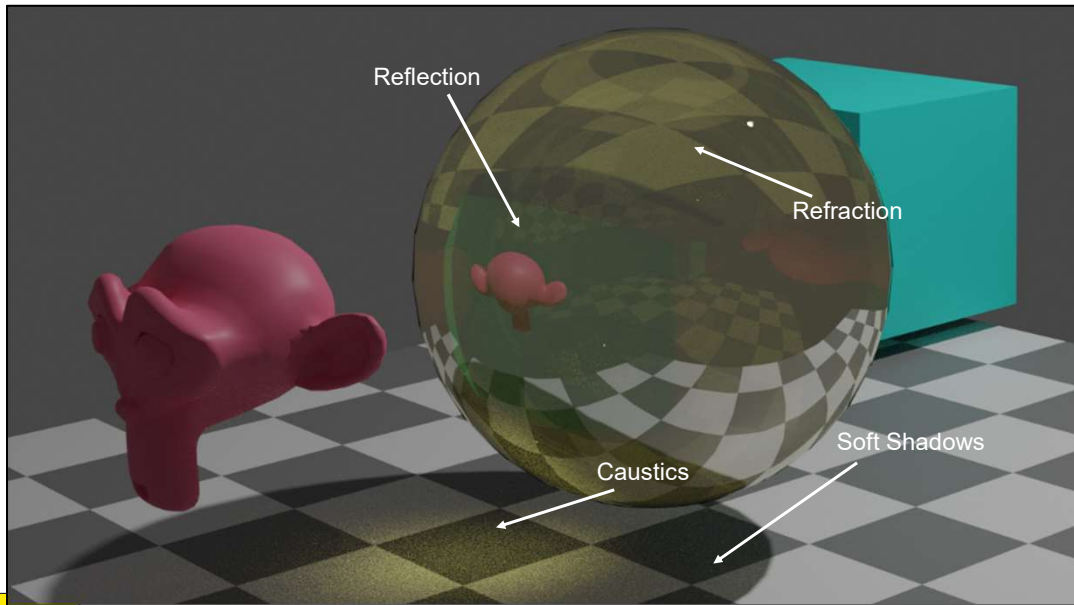


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Physically-Based Rendering using the Blender Cycles Renderer

55

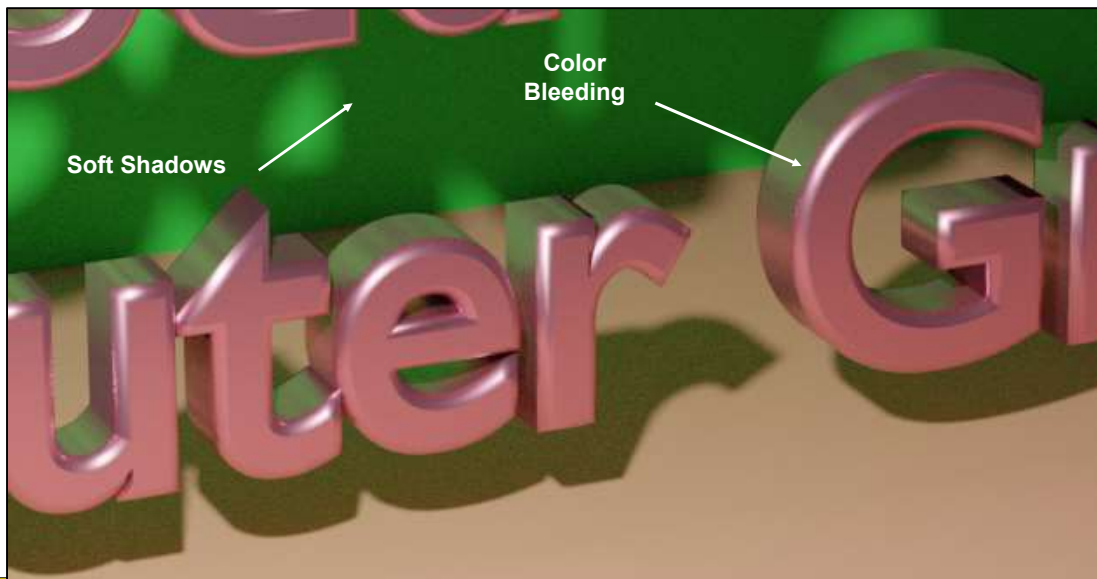


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An Example from the Title Slide

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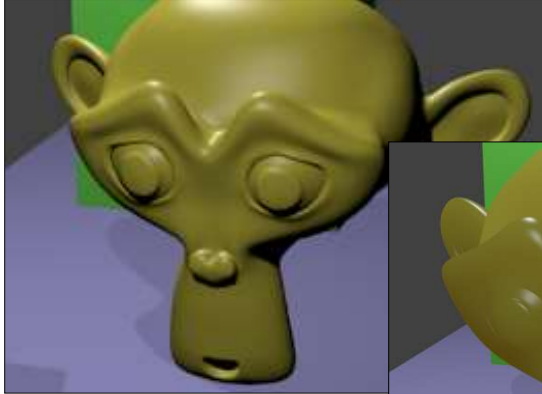
56

Subsurface Scattering

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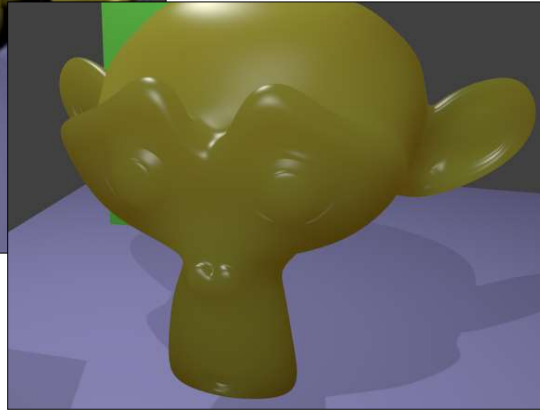
SS models light bouncing around *within* an object before coming back out.

This is a good way to represent skin, wax, milk, paraffin, etc.



Original rendering

With Subsurface Scattering



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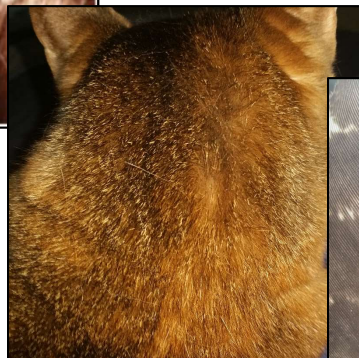
57

Tricky Lighting Situations

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Hair



Fur

Feathers



Watch for these at the conference and in CG movies!



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An Neat Global Illumination-ish Trick: Screen Space Ambient Occlusion (SSAO)

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Kitware



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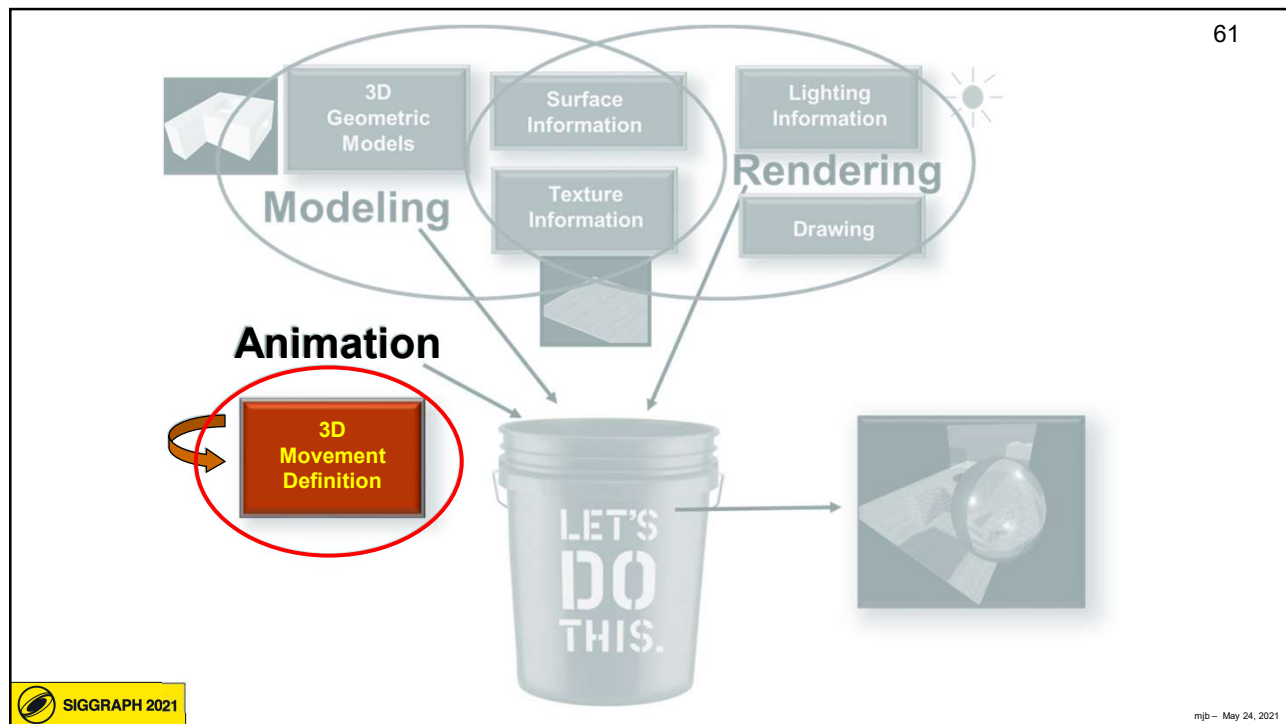
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Creating the motion you want

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Animation

Rendering is the process of giving motion to your geometric modes. Again, there are questions you need to ask first:

- Why am I doing this?
- Do I want the animation to obey the real laws of physics?
- Am I willing to “fake” the physics to get the objects to *want* to move in a way that I tell it?
- Do I have specific key positions I want the objects to pass through no matter what?
- Do I want to simply record the motion of a real person, animal, etc., and then play it back?

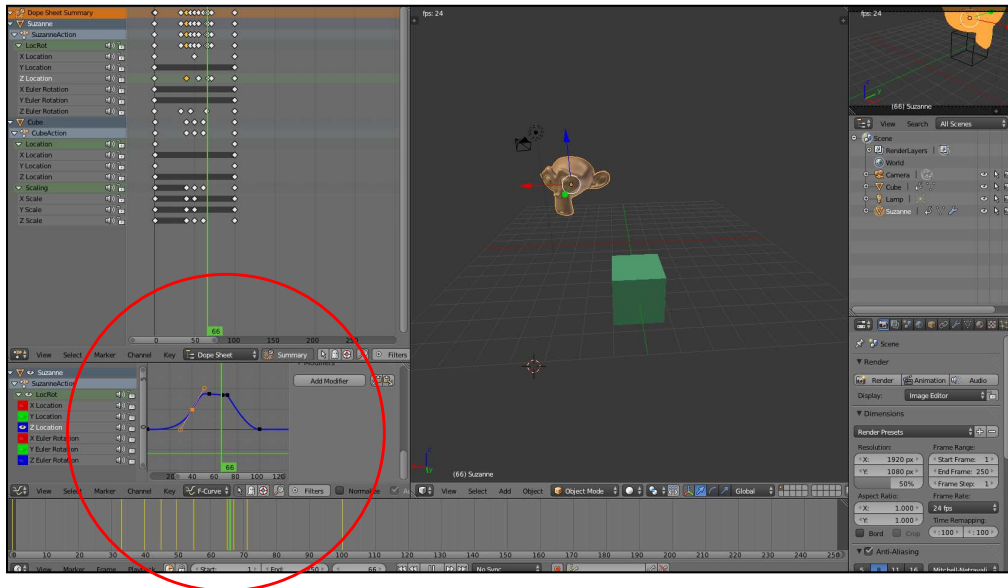
Want to experiment with a free animation program?
 Want some notes on how to get started?
<http://cs.oregonstate.edu/~mjb/blender>

A SIGGRAPH 2021 logo is in the bottom left, and 'mjb - May 24, 2021' is in the bottom right.

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Keyframe Animation

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Forcing the geometry to smoothly pass through key positions

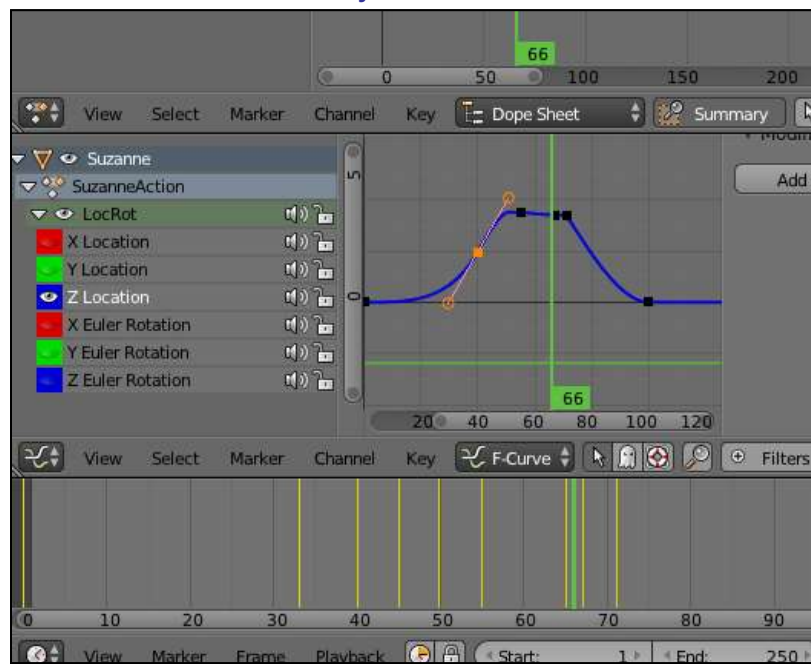


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Keyframe Animation

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anim2.mp4



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A simple C++ class can do it all for you

class Keytimes:

```
void AddTimeValue( float time, float value );
float GetFirstTime( );
float GetLastTime( );
int GetNumKeytimes( );
float GetValue( float time );
void PrintTimeValues( );
```

Find this code (keytime.h, keytime.cpp) on:

<http://cs.oregonstate.edu/~mjb/whirlwind>



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```
Keytimes Xpos;

int
main( int argc, char *argv[ ] )
{
    Xpos.AddTimeValue( 0.0, 0.000 );
    Xpos.AddTimeValue( 2.0, 0.333 );
    Xpos.AddTimeValue( 1.0, 3.142 );
    Xpos.AddTimeValue( 0.5, 2.718 );

    for( float t = 0.; t <= 2.01; t += 0.1 )    // just to show the example – we don't really use a float in a for-loop
    {
        float v = Xpos.GetValue( t );
        fprintf( stderr, "%8.3ft%8.3fn", t, v );
    }
}
```



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DIY KeyTime Animation

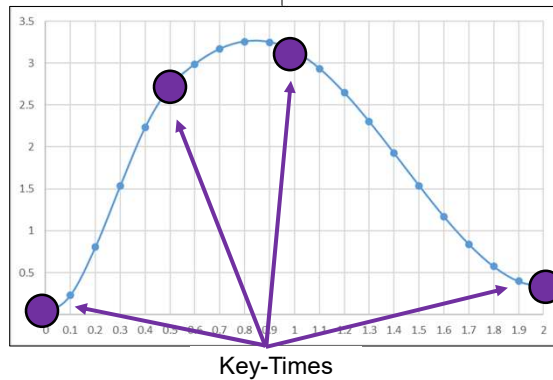
67

```
( 0.00, 0.000)
( 0.00, 0.000) ( 2.00, 0.333)
( 0.00, 0.000) ( 1.00, 3.142) ( 2.00, 0.333)
( 0.00, 0.000) ( 0.50, 2.718) ( 1.00, 3.142) ( 2.00, 0.333)
```

4 time-value pairs

Time runs from 0.000 to 2.000

0.000	0.000
0.100	0.232
0.200	0.806
0.300	1.535
0.400	2.234
0.500	2.718
0.600	2.989
0.700	3.170
0.800	3.258
0.900	3.250
1.000	3.142
1.100	2.935
1.200	2.646
1.300	2.302
1.400	1.924
1.500	1.539
1.600	1.169
1.700	0.840
1.800	0.574
1.900	0.397
2.000	0.333



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Using the System Clock for Timing in Display()

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```
#define MSEC 10000 // i.e., 10 seconds
Keytimes Xpos, Ypos, Zpos;
Keytimes ThetaX, ThetaY, ThetaZ;

...

if( AnimationIsOn )
{
    // # msec into the cycle ( 0 - MSEC-1 ):
    int msec = glutGet( GLUT_ELAPSED_TIME ) % MSEC;

    // turn that into a time in seconds:
    float nowTime = (float)msec / 1000.;
    glPushMatrix( );
    glTranslatef( Xpos.GetValue( nowTime ), Ypos.GetValue( nowTime ), Zpos.GetValue( nowTime ) );
    glRotatef( ThetaX.GetValue( nowTime ), 1., 0., 0. );
    glRotatef( ThetaY.GetValue( nowTime ), 0., 1., 0. );
    glRotatef( ThetaZ.GetValue( nowTime ), 0., 0., 1. );
    << draw the object >>
    glPopMatrix( );
}
```

Number of msec in the animation cycle

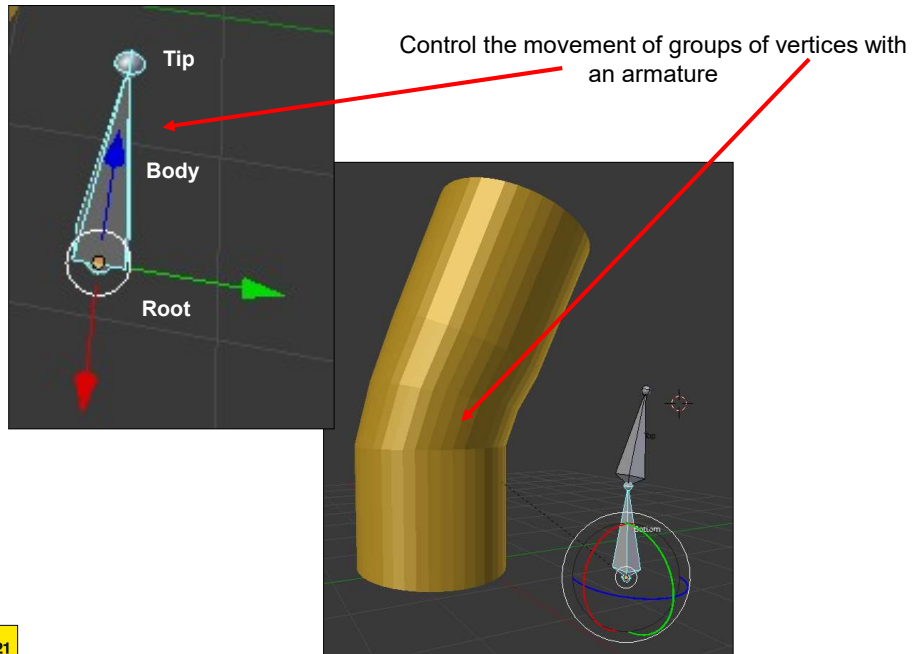


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Rigging Animation

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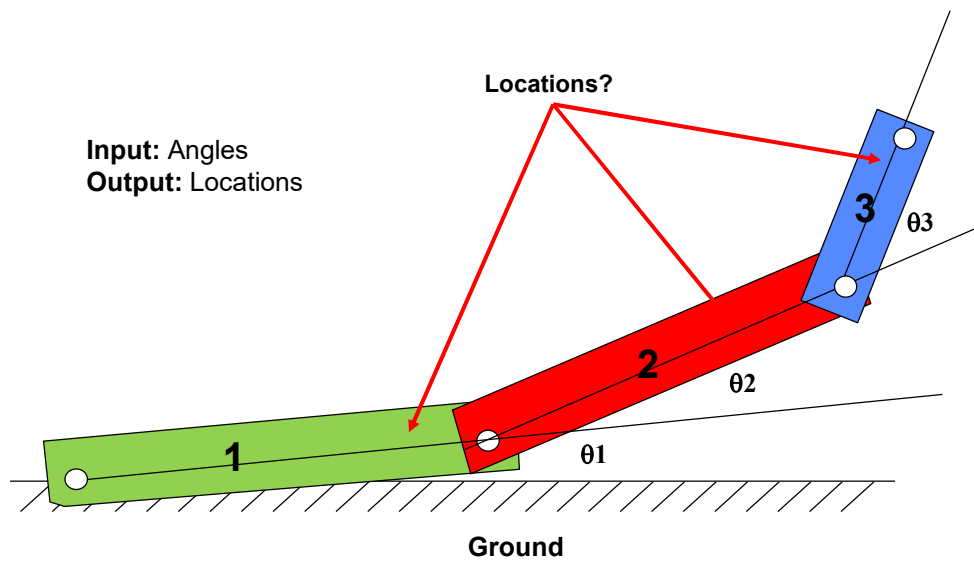


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Forward Kinematics: Transformation Hierarchies

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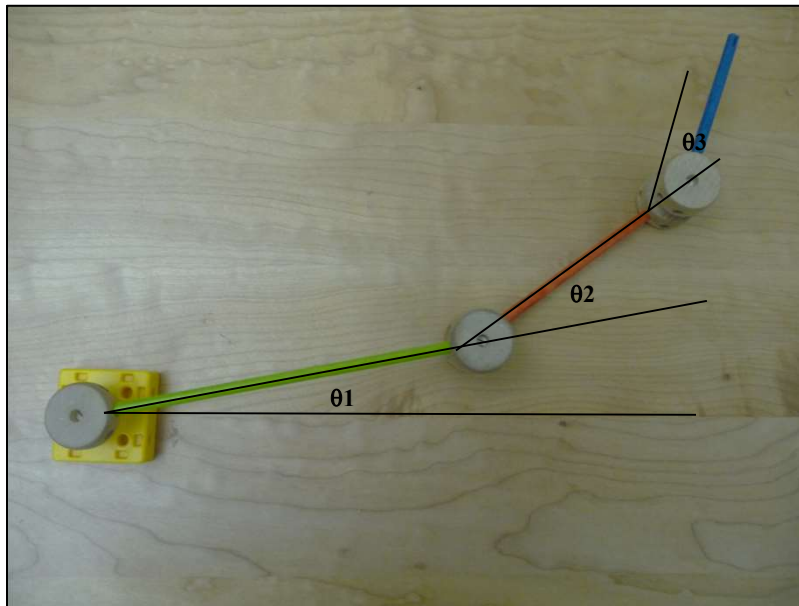


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Forward Kinematics: Change Parameters – Things Move (All Children Understand This)

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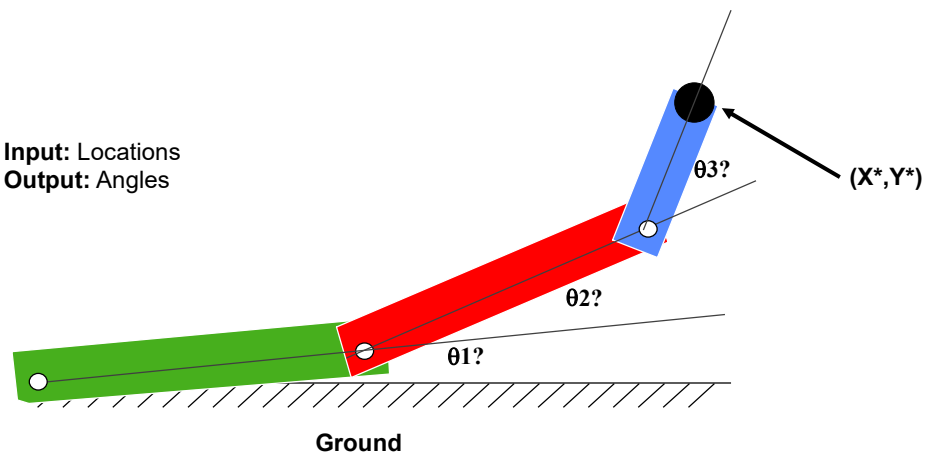
Inverse Kinematics

72

Forward Kinematics solves the problem “if I know the link transformation parameters, where are the links?”.

Inverse Kinematics (IK) solves the problem “If I know where I want the end of the chain to be (X^*, Y^*) , what transformation parameters will put it there?”

Input: Locations
Output: Angles

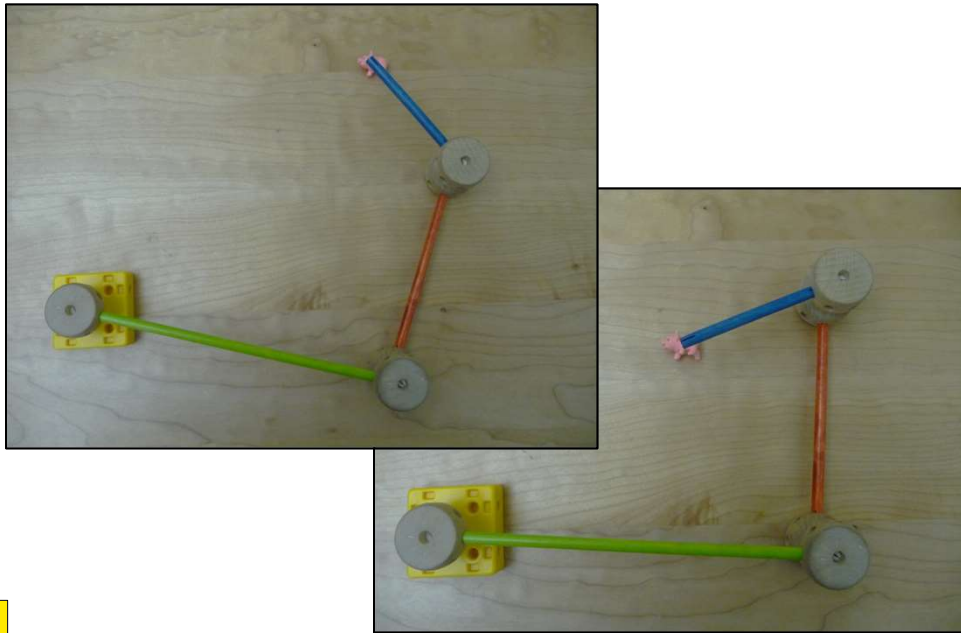


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Inverse Kinematics (IK): Things Need to Move – What Parameters Will Make Them Do That?

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Animating a Human-ish Form

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Start with this ...



... and turn it into a kinematic model:

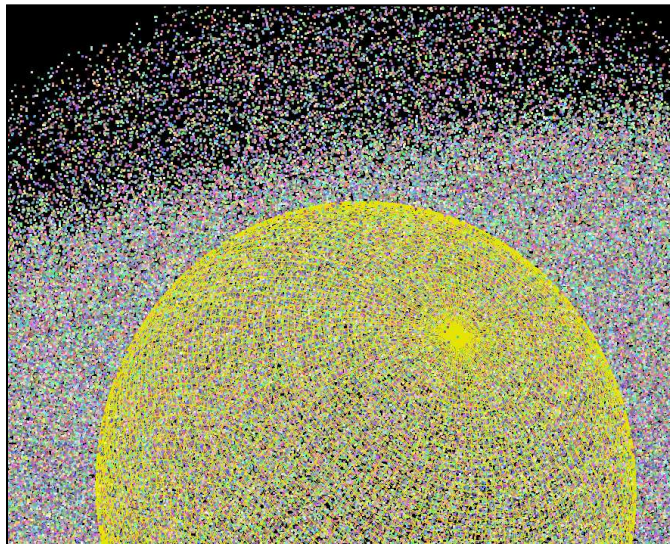


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Particle Systems:
A Cross Between Modeling and Animation?

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gpu_particles.mp4

Check out this movie! These are particles animated on a GPU.



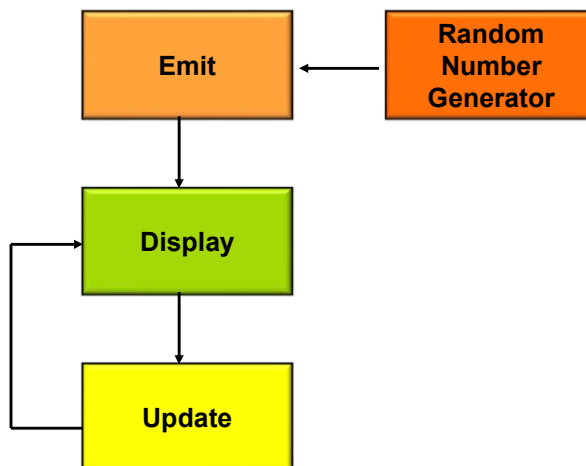
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Particle Systems:
A Cross Between Modeling and Animation?

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The basic process is:

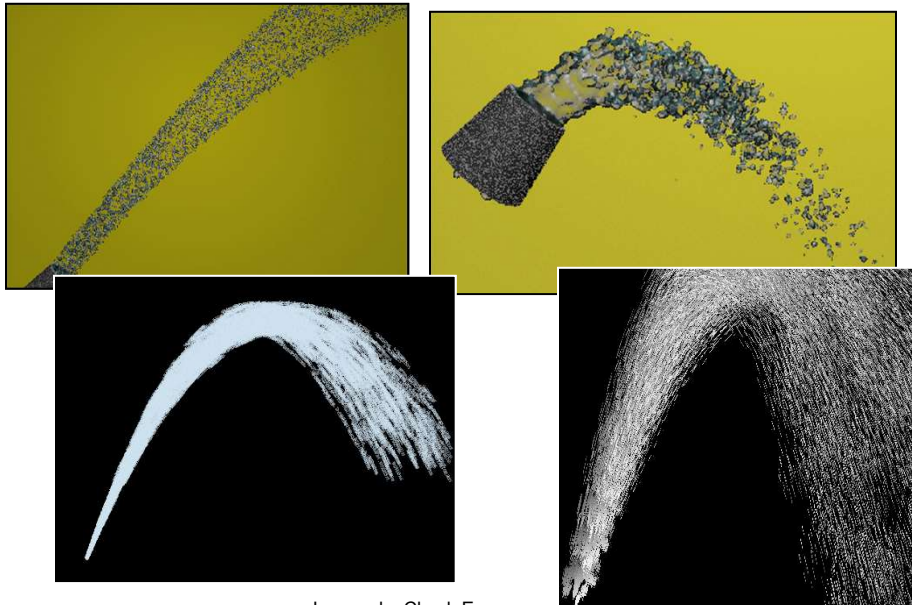


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Particle Systems Examples

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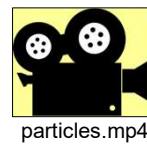
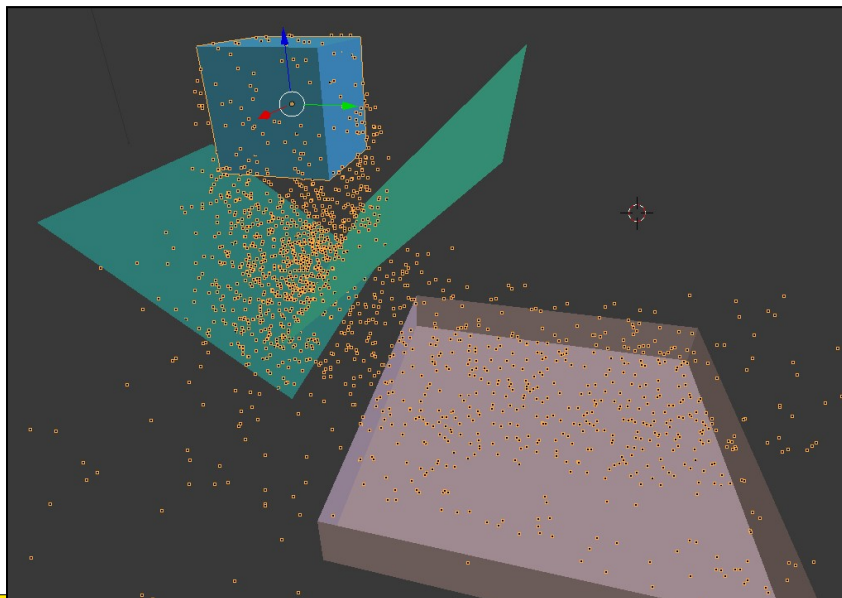
Images by Chuck Evans

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Particle Systems Examples

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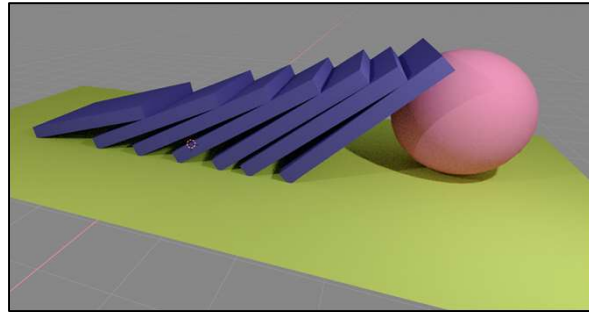
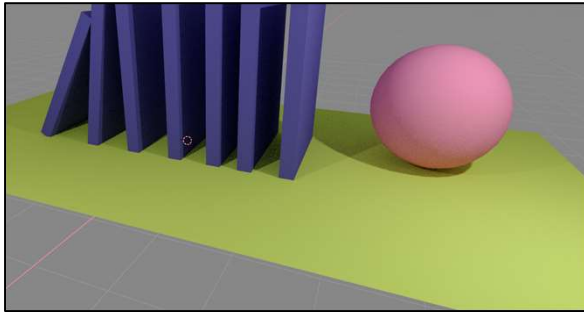


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Animating using Rigid-body Physics

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Newton's second law:
force = mass * acceleration

or:

acceleration = force / mass

Newton's Second Law



dominos2.mp4

In order to make this work, you need to supply physical properties such as mass, center of mass, moment of inertia, coefficients of friction, coefficients of restitution, etc.

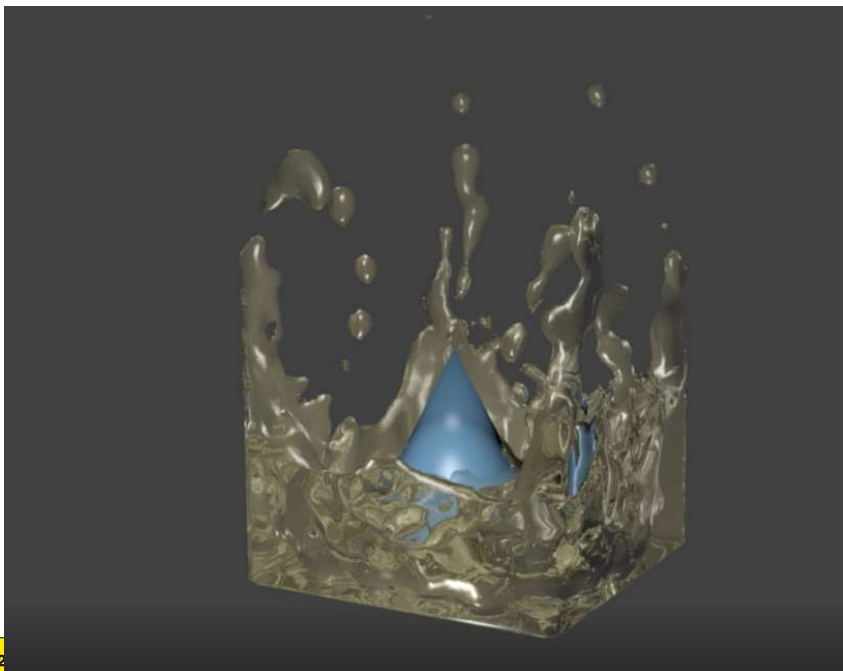


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Animating using Fluid Physics

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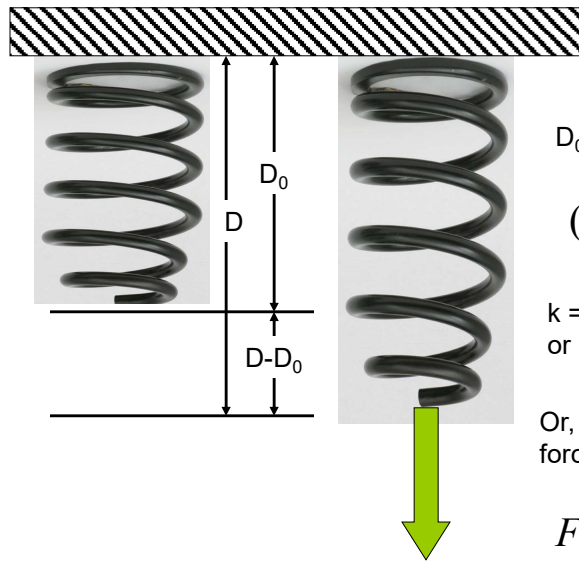


fluid.avi



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D_0 = unloaded spring length

$$(D - D_0) = \frac{F}{k}$$

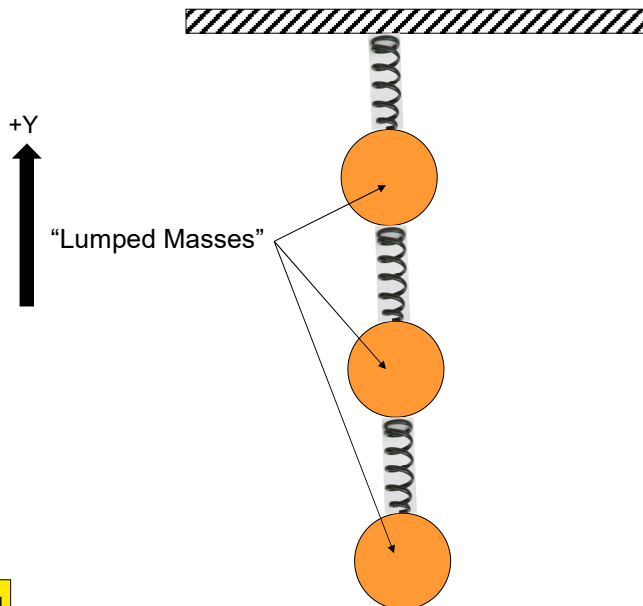
k = **spring stiffness** in Newtons/meter or pounds/inch

Or, if you know the displacement, the force exerted by the spring is:

$$F = k(D - D_0)$$

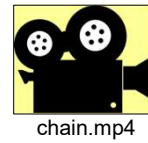
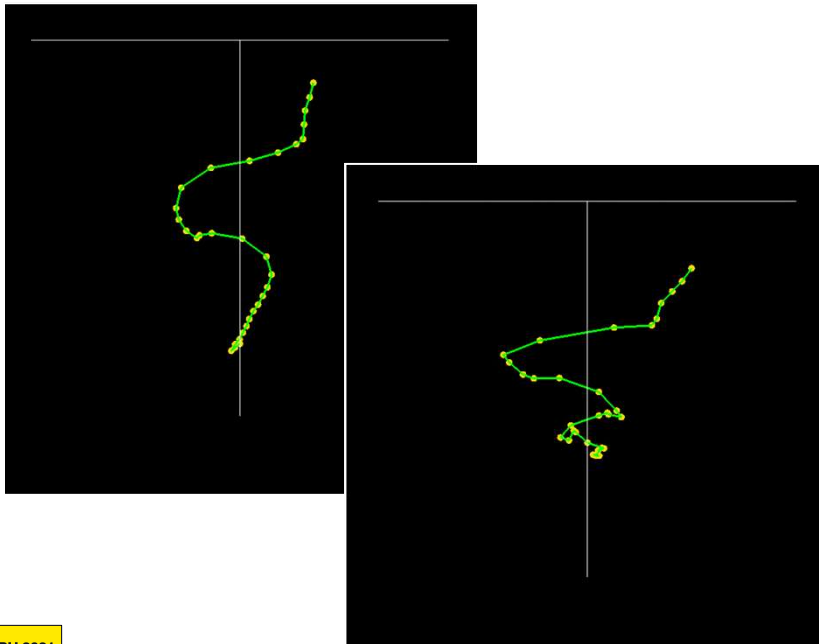
Force = F

This is known as **Hooke's Law**



Simulating a Bouncy Chain

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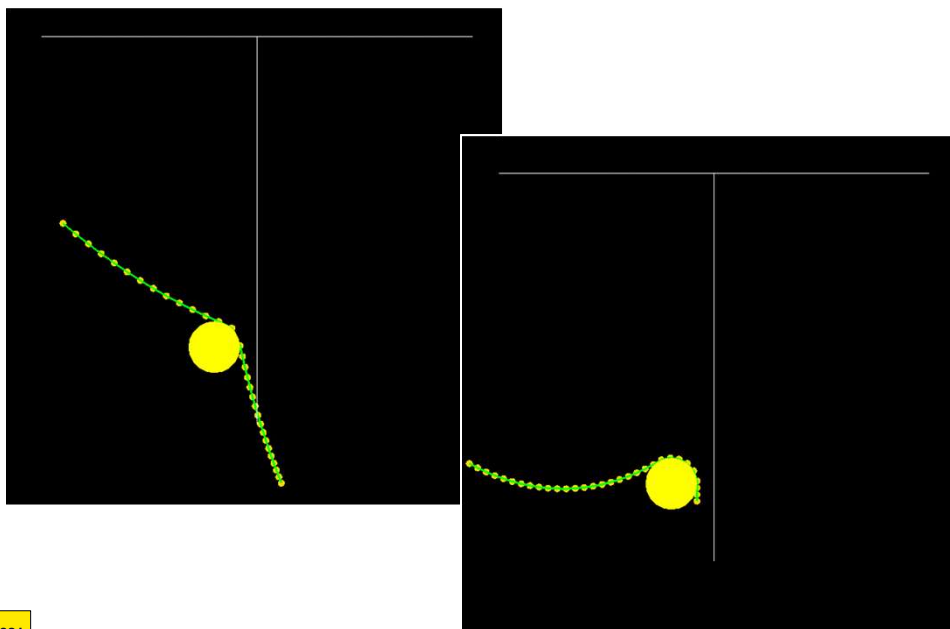


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Placing a Physical Barrier in the Scene

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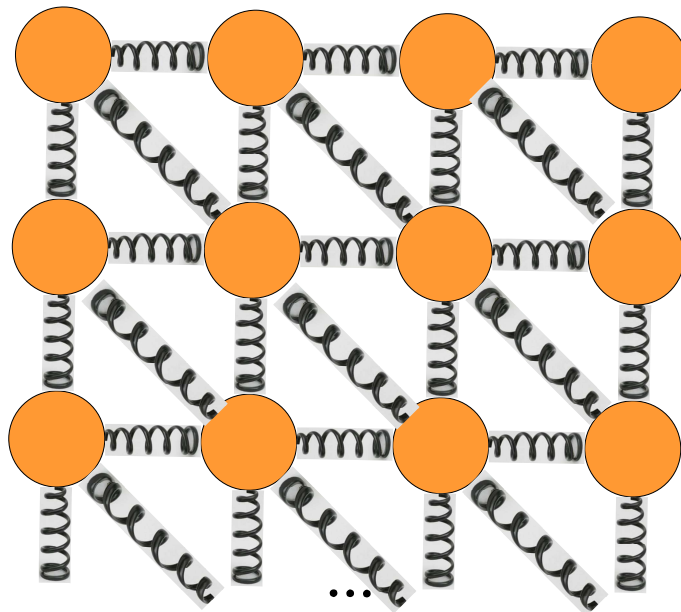


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Animating Cloth

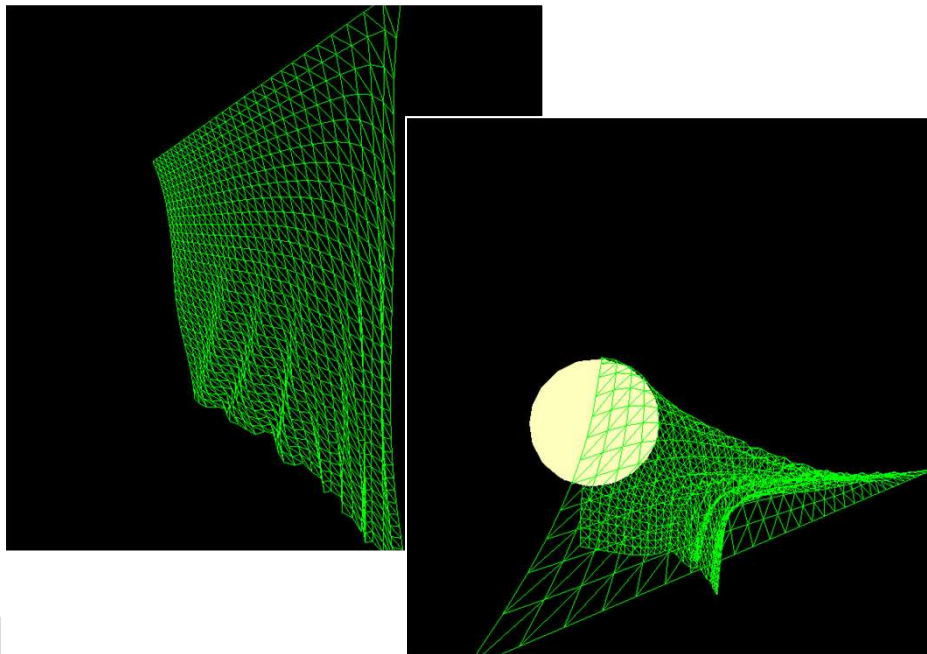
85



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Cloth Examples

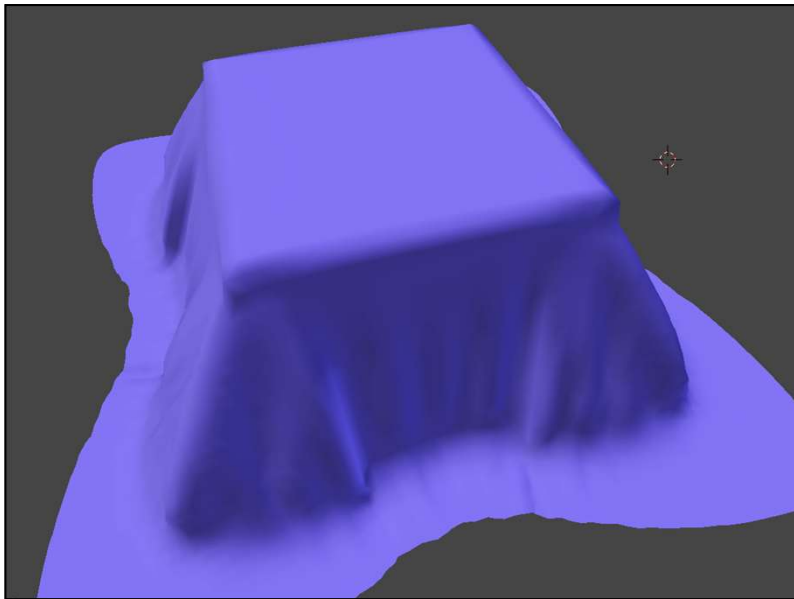
86



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Cloth Example

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cloth.mp4



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Functional Animation – “Fake Physics”

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The Challenge: animate a collection of objects, each trying to move to a target, but without colliding with each other

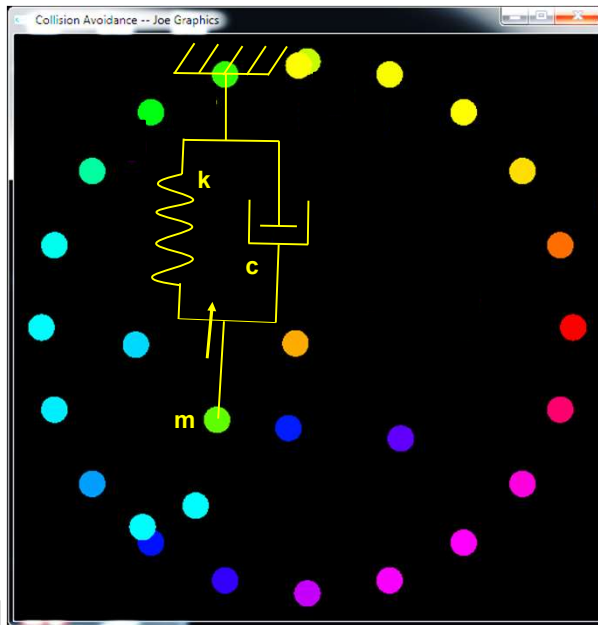


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Functional Animation:
Make the Object *Want* to Move Towards a Goal Position . . .

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$$m\ddot{x} + c\dot{x} + kx = 0$$

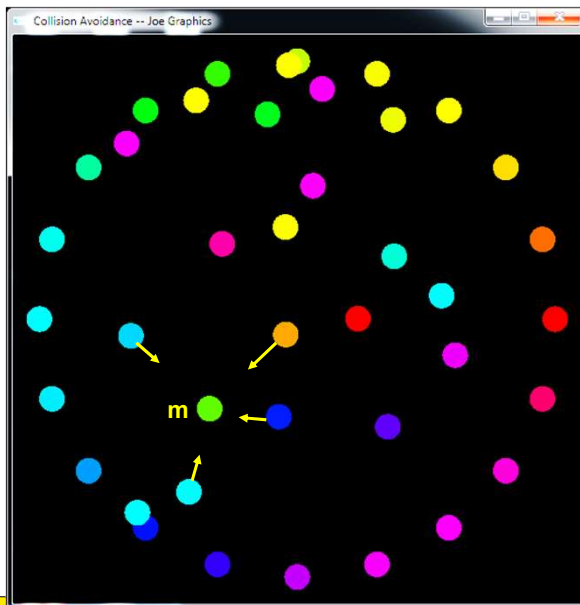


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Functional Animation:
. . . While Making it *Want* to Keep Away from all other Objects

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$$m\ddot{x} = \sum F_{repulsive}$$

$$F_{repulsive} = \frac{C_{repulse}}{d^{Power}}$$

Repulsion Coefficient

Distance between the boundaries of the 2 bodies

Repulsion Exponent

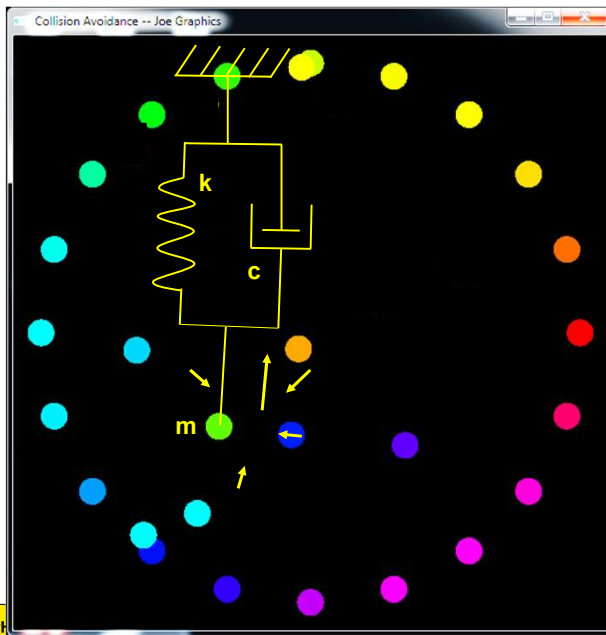


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Total Goal – Make the Free Body Move Towards its Final Position
While Being Repelled by the Other Bodies

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$$m\ddot{x} + c\dot{x} + kx = \sum F = \sum F_{repulsive}$$

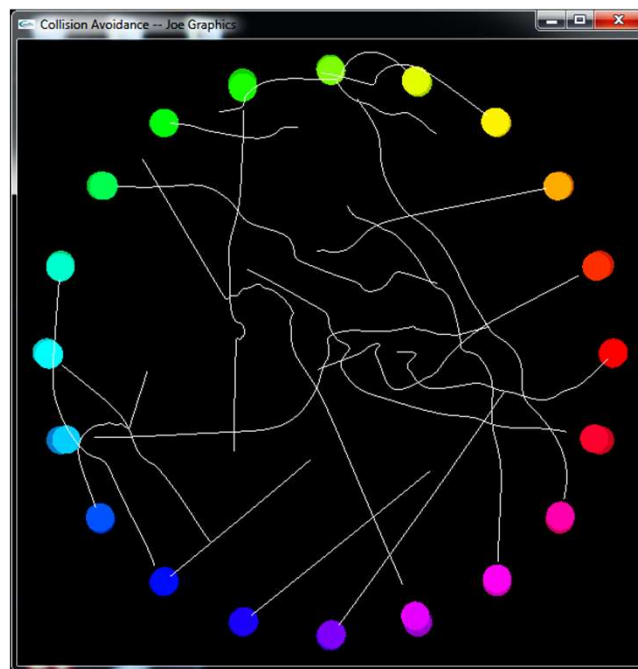


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Functional Animation

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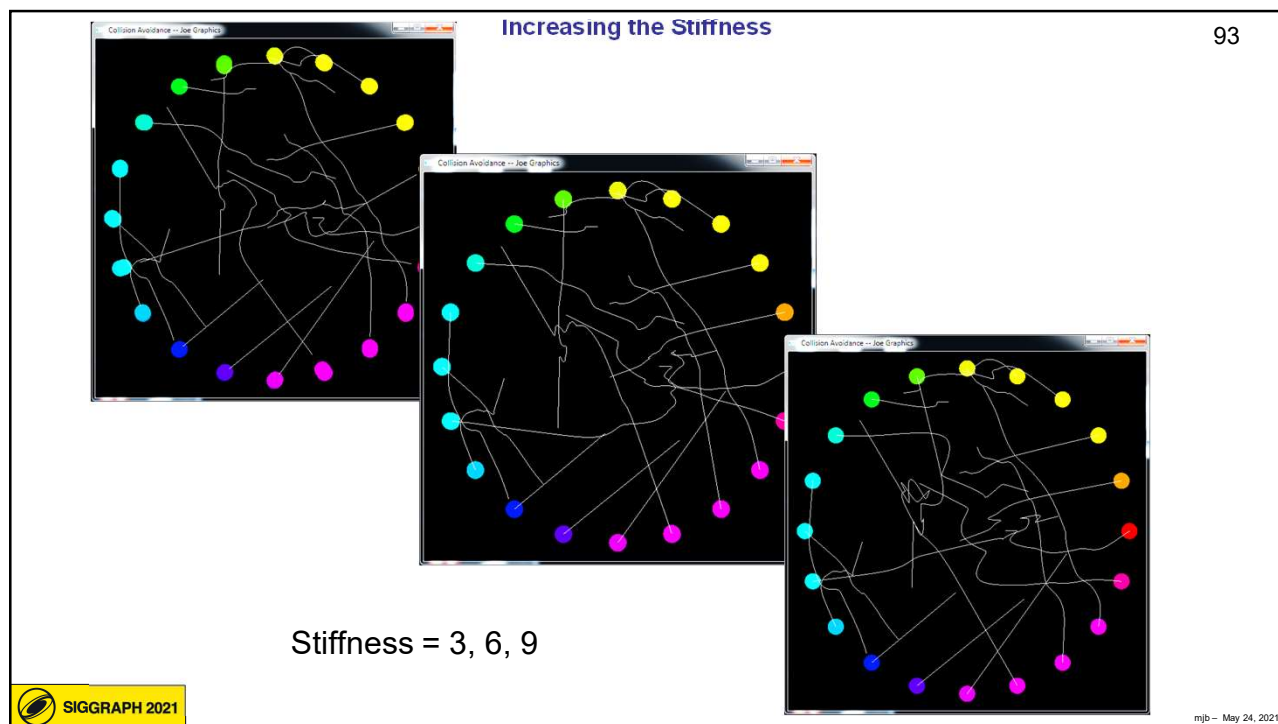


avoid.mp4

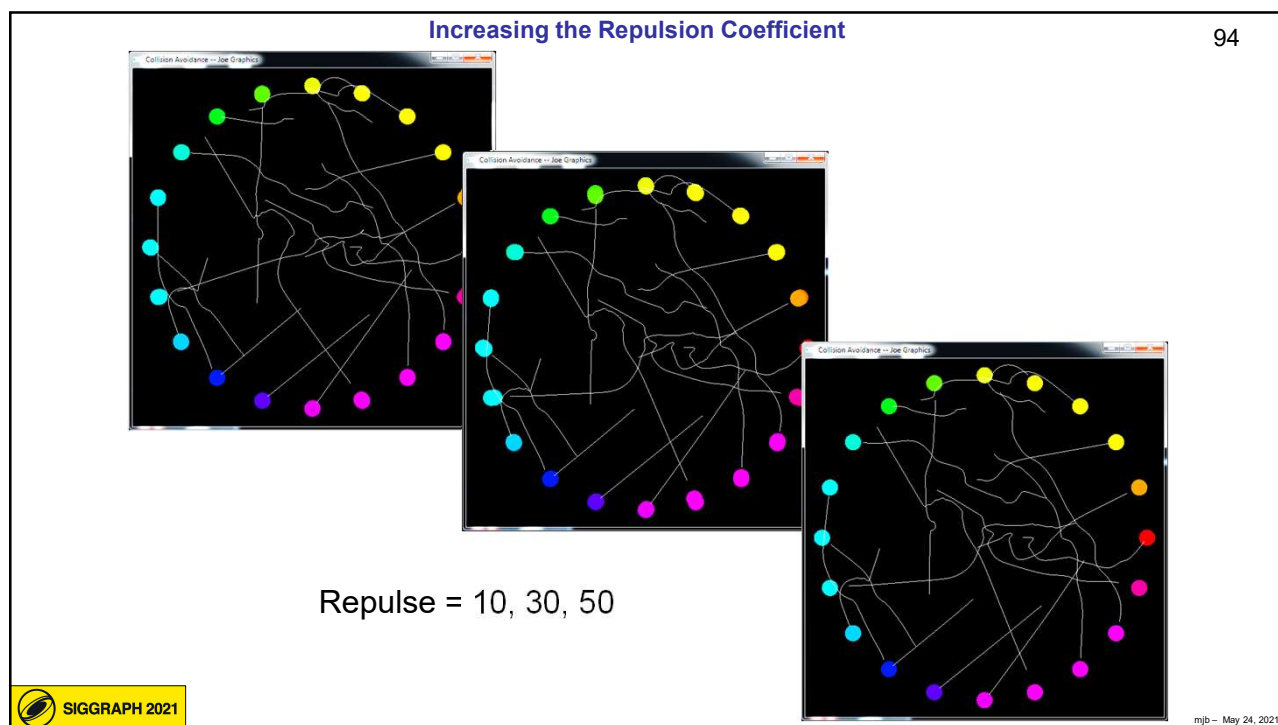


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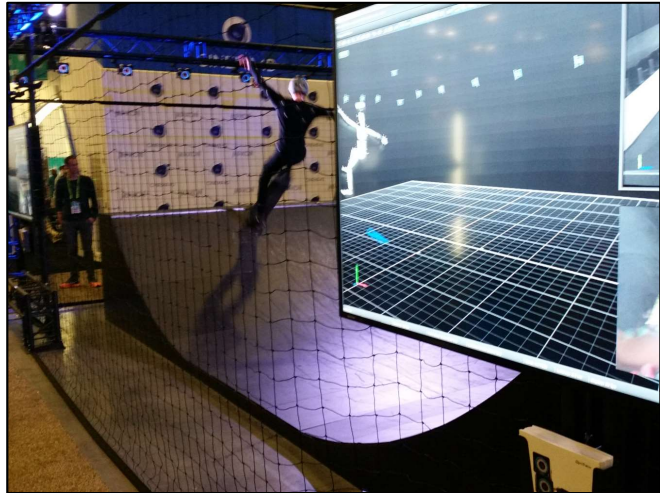
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Motion Capture ("MoCap") as an Input for Animation

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Even Animals can be MoCapped

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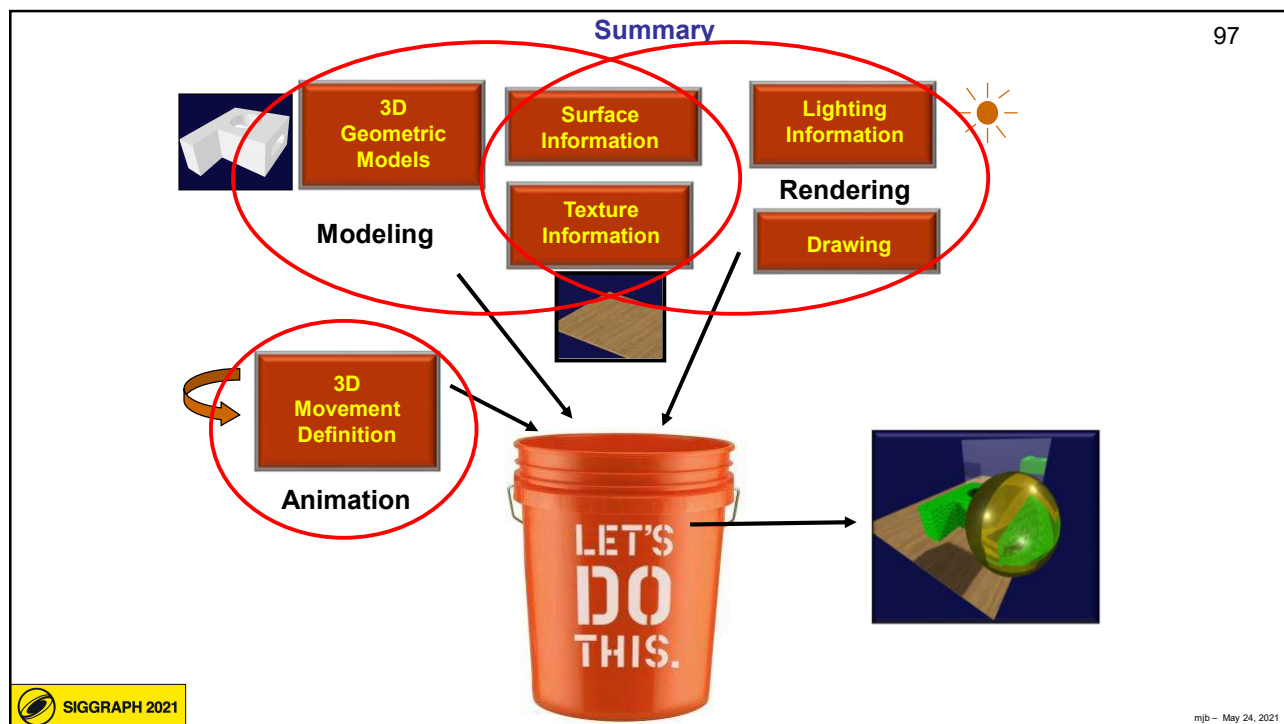


https://www.youtube.com/watch?v=zyq_LQrHpoo



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Conclusions !

- SIGGRAPH moments will never come again. Well, this is usually true, but through the 2021 videos, they might. But, be aware of what is going to be archived and what isn't. And, if it is to be archived, how long will you have access to it?
- Especially take advantage of the not-to-be-archived or not-to-be-archived-for-long events because you cannot re-live them forever.
- Combine what you have just learned here with what else you learn at the conference and relate them to your career and life goals.
- Have fun!

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Check out the *More Information* Document!

**Where to Find More Information about
Computer Graphics and Related Topics**

Mike Bailey
Oregon State University

1. References

1.1 General Computer Graphics

SIGGRAPH Online Bibliography Database:
<http://www.siggraph.org/learn/computer-graphics-bibliography-database>

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 **SIGGRAPH 2021**

A Whirlwind Introduction to Computer Graphics

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