

Developments in Physically-Based Modeling

SIGGRAPH 88

Course Chair:

Alan H. Barr, California Institute of Technology, Pasadena, California

Speakers:

John F. Abel, Cornell University, Ithaca, New York ✓

Alan H. Barr, California Institute of Technology, Pasadena, California ✓

Ronen Barzel, California Institute of Technology, Pasadena, California

Donald P. Greenberg, Cornell University, Ithaca, New York ✓

John C. Platt, California Institute of Technology, Pasadena, California ✓

Craig W. Reynolds, Symbolics Inc., Westwood, California ✓

COURSE #27

Contents

1	Introduction to Physically-Based Modeling	A-1
1.1	Introduction to Physically-Based Modeling, (<i>Barr</i>)	A-1
1.2	Teleological Modeling, (<i>Barr</i>)	B-1
1.3	Another Introduction to Numerical Analysis, (<i>Platt</i>)	C-1
1.4	Structural Analysis by Finite Element Methods, (<i>Abel</i>)	D-1
2	Dynamic Constraints	E-1
2.1	Controlling Rigid Bodies with Dynamic Constraints, (<i>Barzel, Barr</i>)	E-1 ✓
2.2	Controlling Dynamic Simulation with Kinematic Constraints, Behavior Functions, and Inverse Dynamics, (<i>Isaacs, Cohen</i>)	F-1
2.3	Not Bumping Into Things, (<i>Reynolds</i>)	G-1
2.4	Flocks, Herds, and Schools: A Distributed Behavioral Model, (<i>Reynolds</i>)	H-1
2.5	Computational Techniques for the Self Assembly of Large Space Structures, (<i>Barr, Von Herzen, Barzel, Snyder</i>)	I-1
3	Flexible Bodies	J-1
3.1	Global and Local Deformations of Solid Primitives, (<i>Barr</i>)	J-1
3.2	Elastically Deformable Models (<i>Platt, Terzopoulos, Fleischer, Barr</i>)	K-1
3.3	Constraint Methods for Flexible Models, (<i>Platt, Barr</i>)	L-1
3.4	Energy Constraints on Parameterized Models, (<i>Wilkin, Fleischer, Barr</i>)	M-1
4	Physically-Based Rendering	N-1
4.1	Physically-Based Rendering Methods: A Radiosity Approach, (<i>Greenberg</i>)	N-1
4.2	The Rendering Equation, (<i>Kajiya</i>)	O-1
4.3	A Radiosity Method for Non-Diffuse Environments, (<i>Immel, Cohen</i>)	P-1